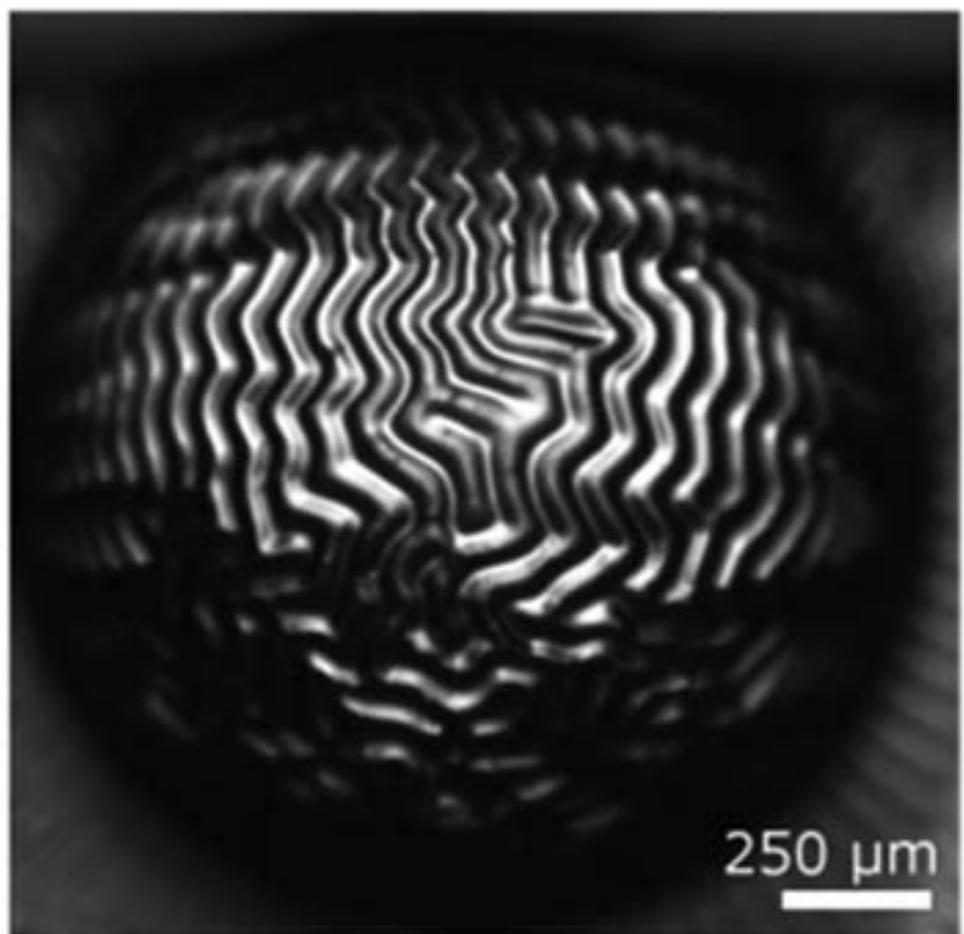
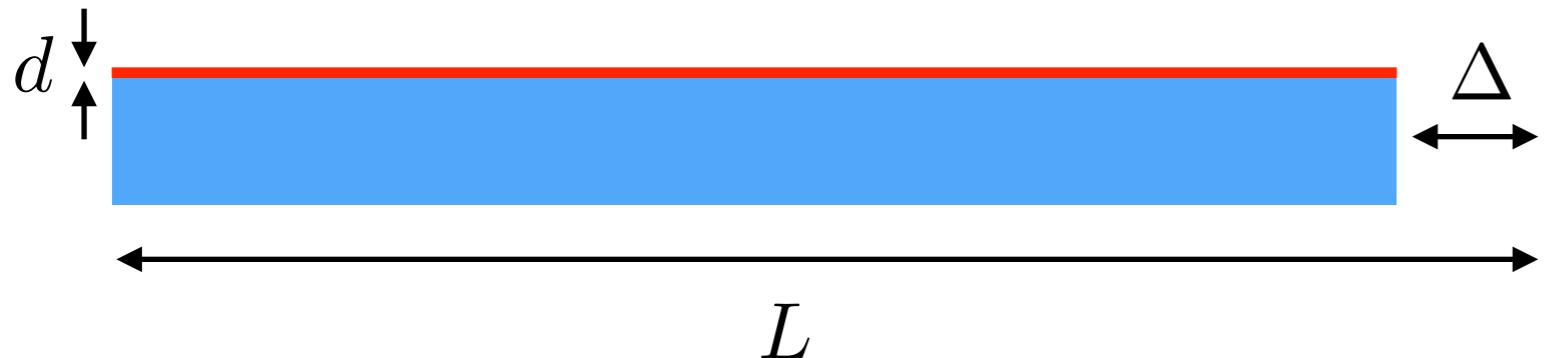


MAE 545: Lecture 6 (2/22)

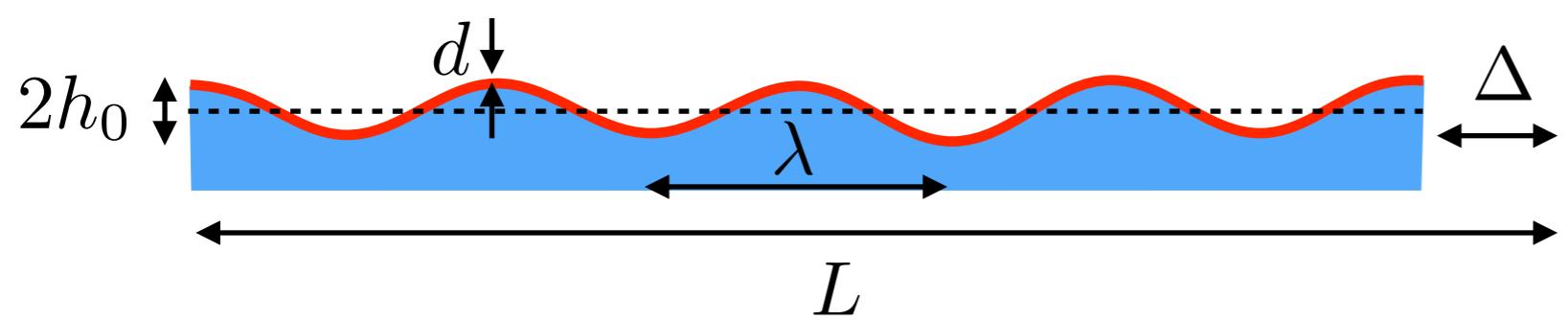
Wrinkled surfaces



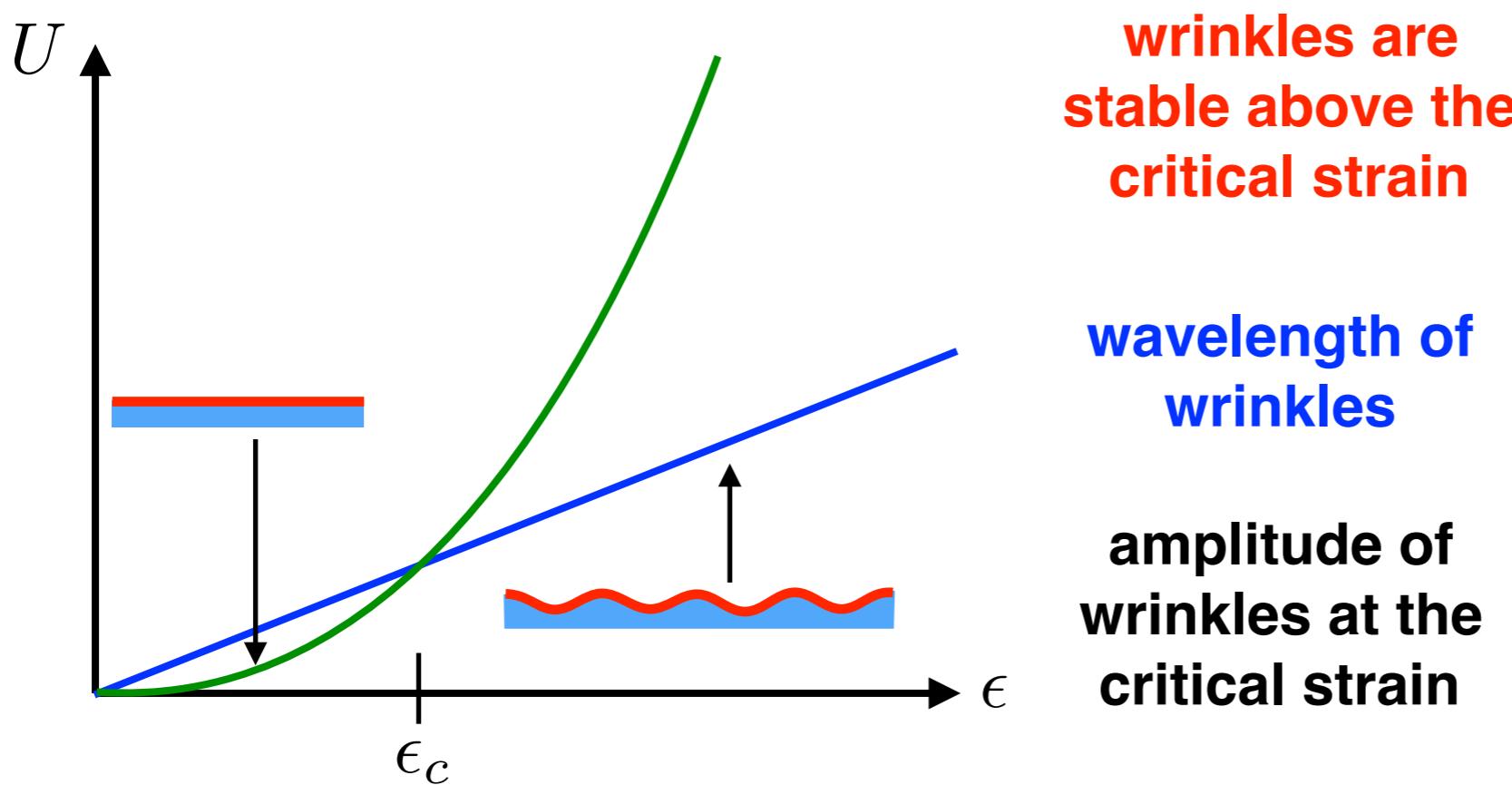
Compression of stiff thin membranes on liquid substrates



$$U_c \sim A \times E_m d \times \epsilon^2$$



$$U_b, U_p \sim A\epsilon \sqrt{E_m d^3 \rho g}$$



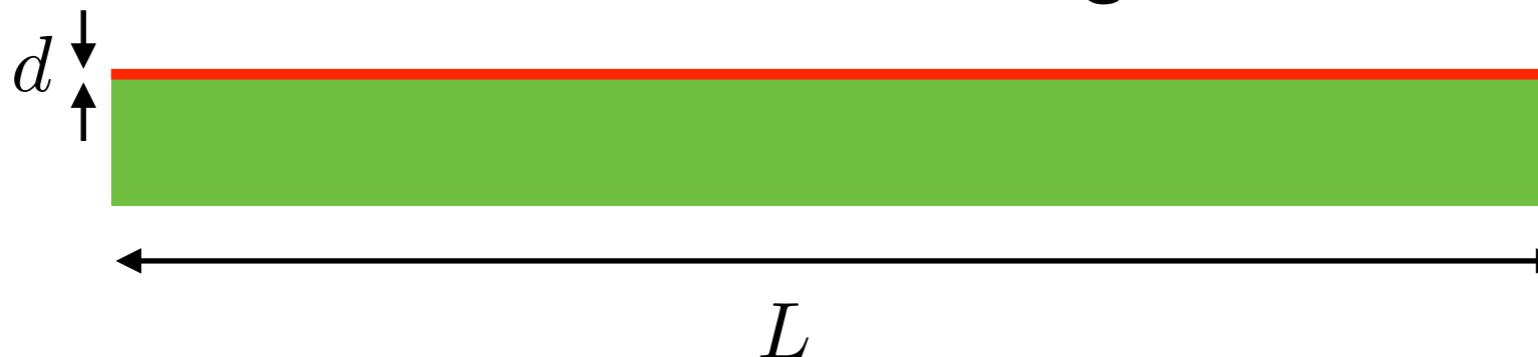
$$\epsilon > \epsilon_c \sim \sqrt{\frac{\rho g d}{E_m}}$$

$$\lambda \sim \left(\frac{E_m d^3}{\rho g} \right)^{1/4}$$

$$h_0^* \sim \lambda \sqrt{\epsilon_c} \sim d$$

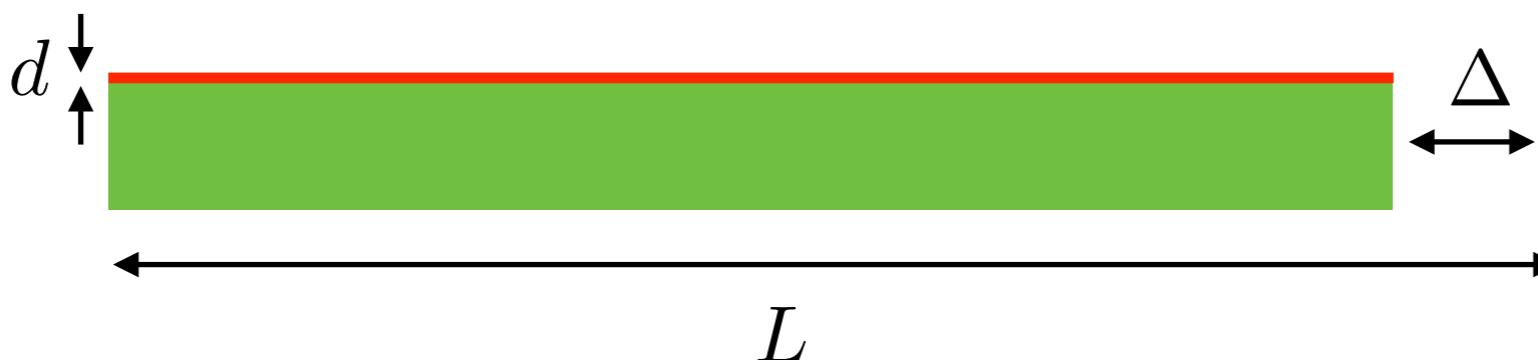
Compression of stiff thin membranes on soft elastic substrates

initial undeformed configuration

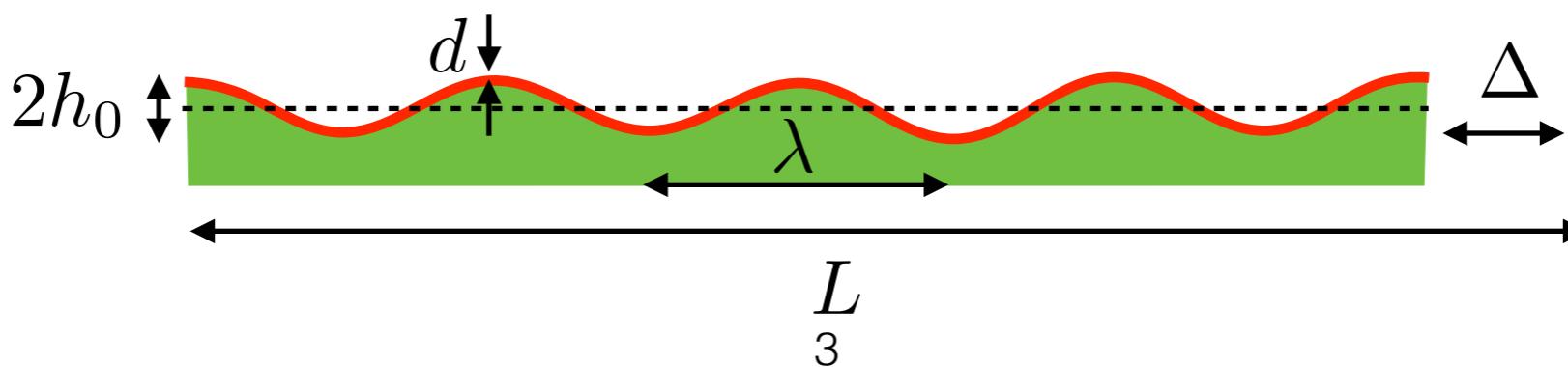


Consider the energy cost for two different scenarios:

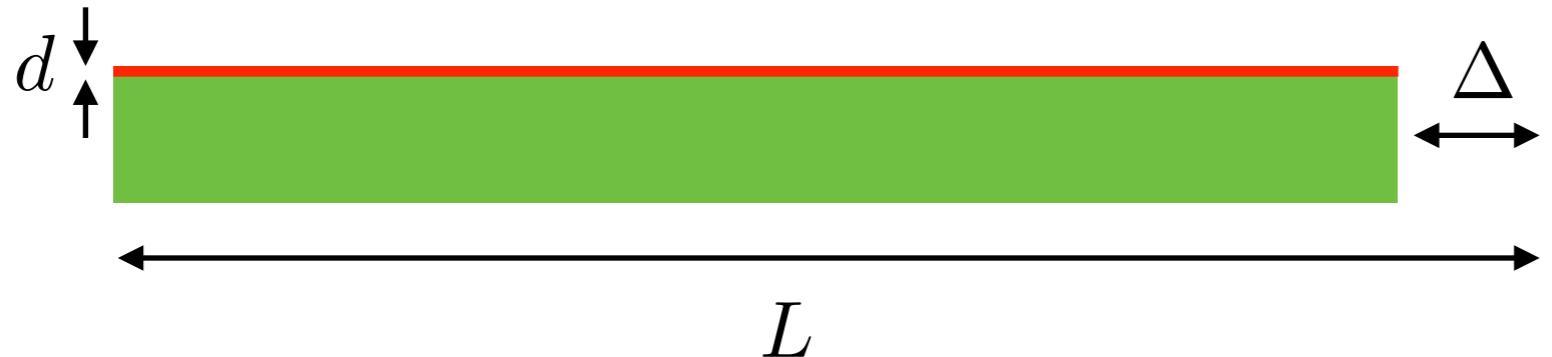
1.) thin membrane is compressed (no bending)



2.) thin membrane is wrinkled (no compression)
additional elastic energy for deformed substrate



Compression of stiff thin membranes on soft elastic substrates



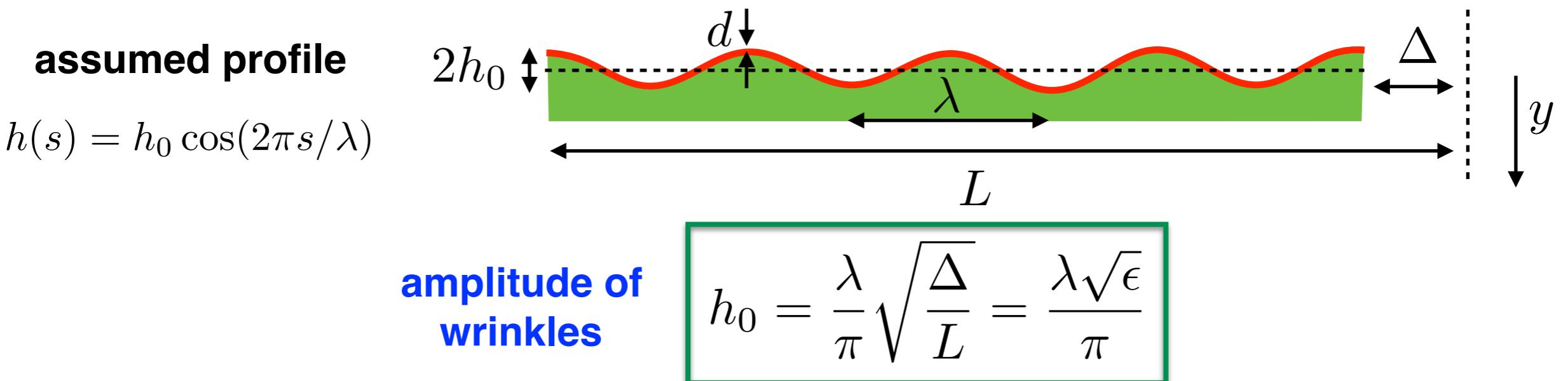
compression energy of thin membrane

$$U_c \sim A \times E_m d \times \epsilon^2$$

membrane area	membrane 3D Young's modulus	strain	substrate 3D Young's modulus
$A = WL$	E_m	$\epsilon = \frac{\Delta}{L}$	E_s $E_s \ll E_m$

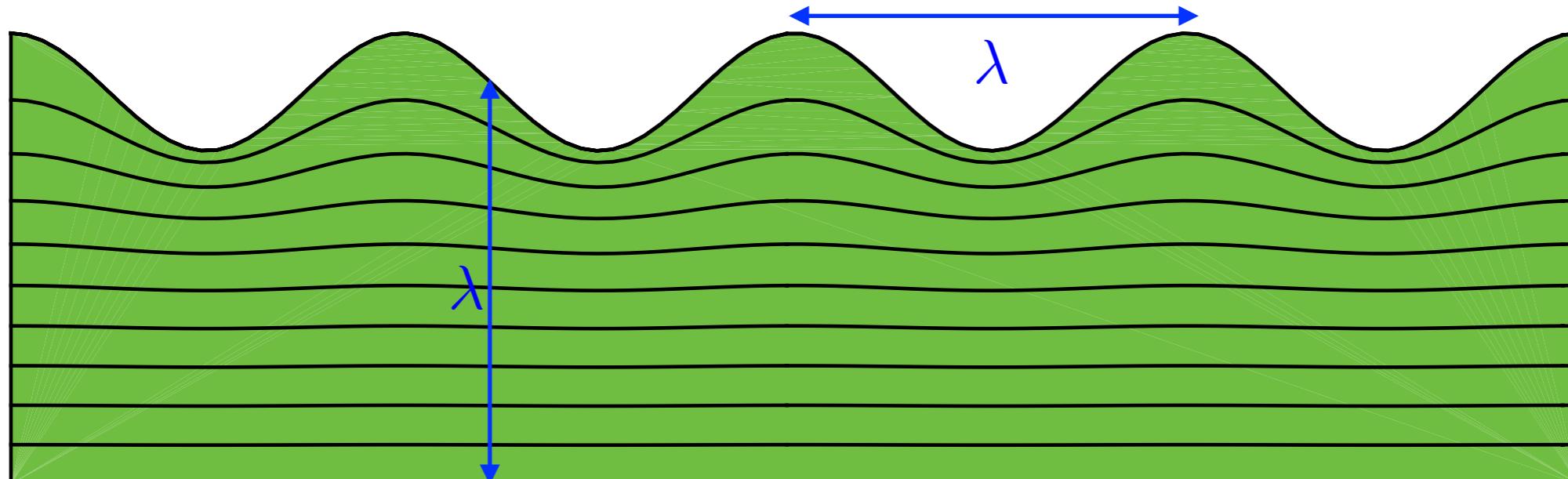
Note: soft elastic substrate is also compressed, but we will measure the substrate elastic energy relative to this base value!

Compression of stiff thin membranes on soft elastic substrates



deformation of the soft substrate decays exponentially away from the surface

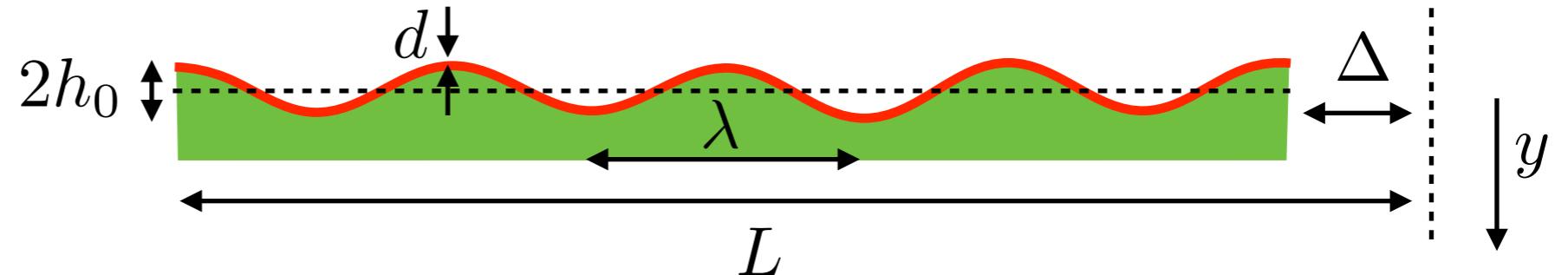
$$h(s, y) \approx h_0 \cos(2\pi s/\lambda) e^{-2\pi y/\lambda}$$



Compression of stiff thin membranes on soft elastic substrates

assumed profile

$$h(s) = h_0 \cos(2\pi s/\lambda)$$



amplitude of wrinkles

$$h_0 = \frac{\lambda}{\pi} \sqrt{\frac{\Delta}{L}} = \frac{\lambda \sqrt{\epsilon}}{\pi}$$

deformation of the soft substrate decays exponentially away from the surface

$$h(s, y) \approx h_0 \cos(2\pi s/\lambda) e^{-2\pi y/\lambda}$$

bending energy of stiff membrane

$$U_b \sim A \times \kappa \times \frac{1}{R^2} \sim A \times E_m d^3 \times \frac{h_0^2}{\lambda^4} \sim \frac{A E_m d^3 \epsilon}{\lambda^2}$$

deformation energy of soft substrate

$$U_s \sim V \times E_s \times \epsilon_s^2 \sim A \lambda \times E_s \times \frac{h_0^2}{\lambda^2} \sim A E_s \lambda \epsilon$$

minimize total energy (U_b+U_s) with respect to λ

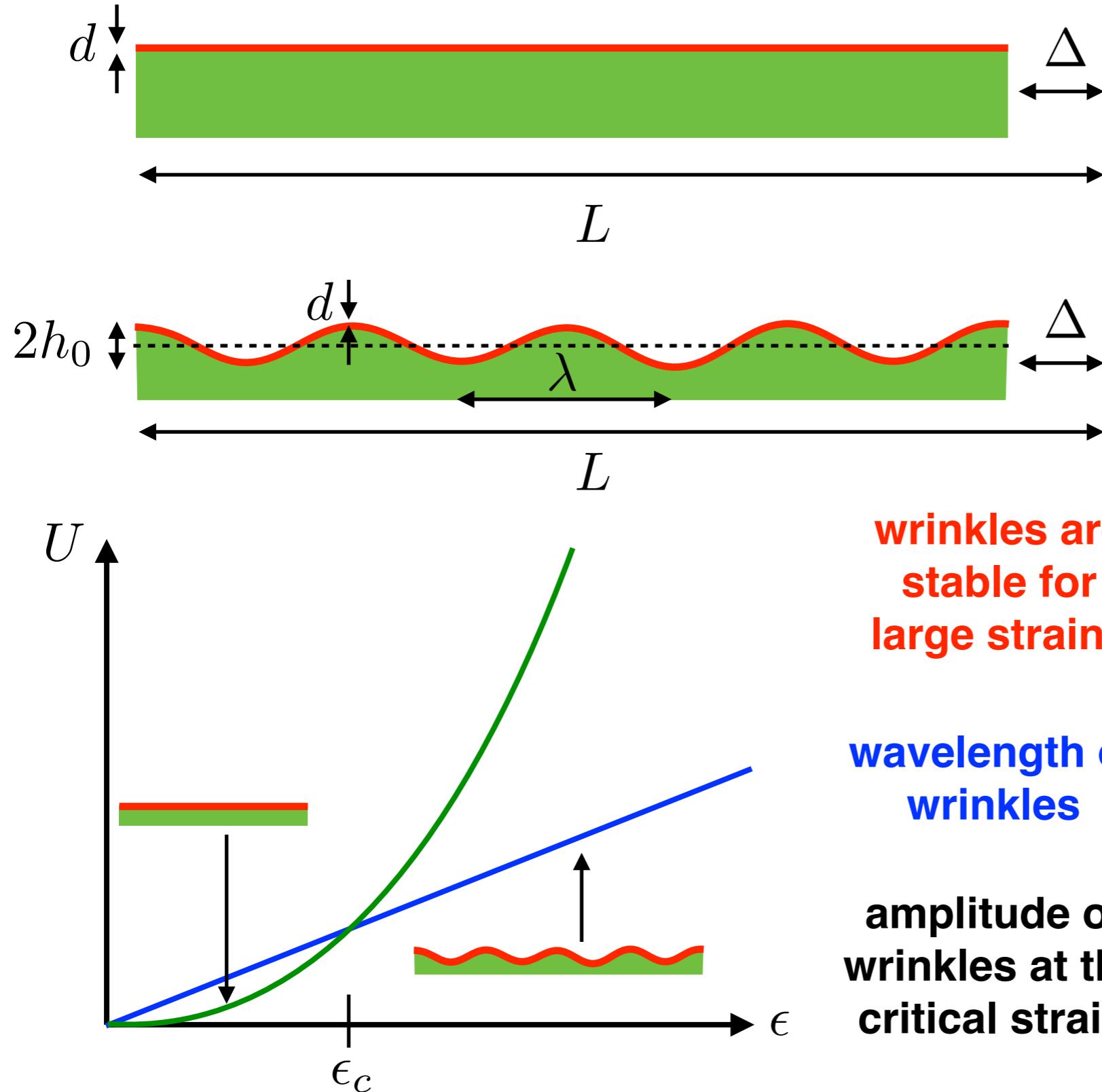


$$\lambda \sim d \left(\frac{E_m}{E_s} \right)^{1/3}$$



$$U_b, U_s \sim A d \epsilon \left(E_s^2 E_m \right)^{1/3}$$

Compression of stiff thin membranes on soft elastic substrates

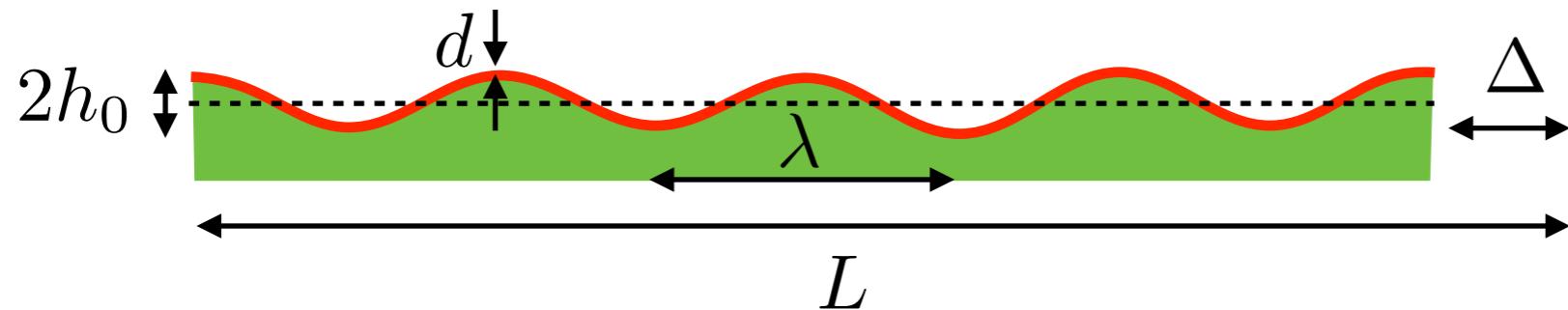


$$\epsilon > \epsilon_c \sim \left(\frac{E_s}{E_m}\right)^{2/3}$$

$$\lambda \sim d \left(\frac{E_m}{E_s}\right)^{1/3}$$

$$h_0^* \sim \lambda \sqrt{\epsilon_c} \sim d$$

Compression of stiff thin membranes on liquid and soft elastic substrates

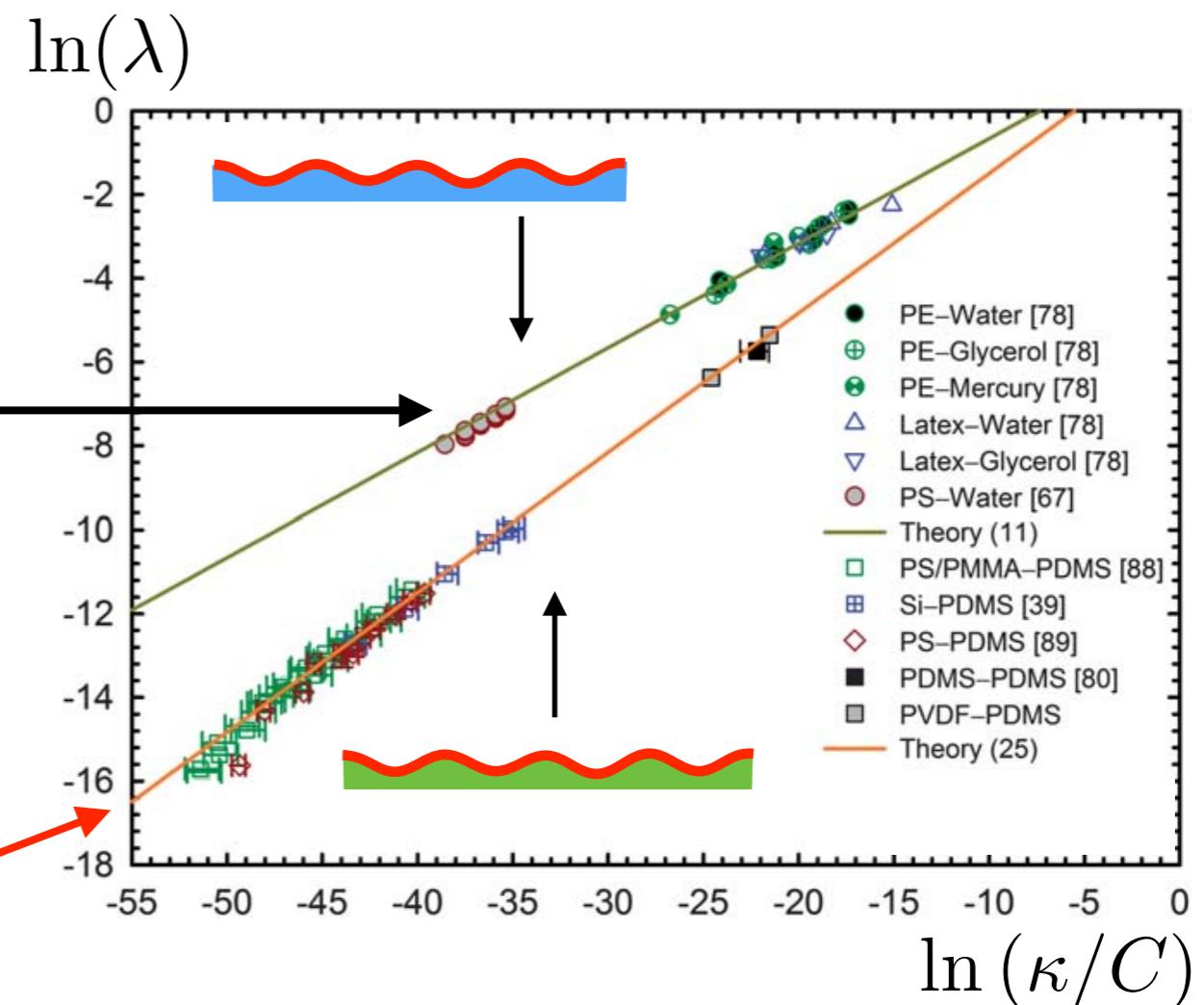


wavelength of wrinkles
on liquid substrates

$$\lambda = 2\pi \left(\frac{\kappa}{\rho g} \right)^{1/4}$$

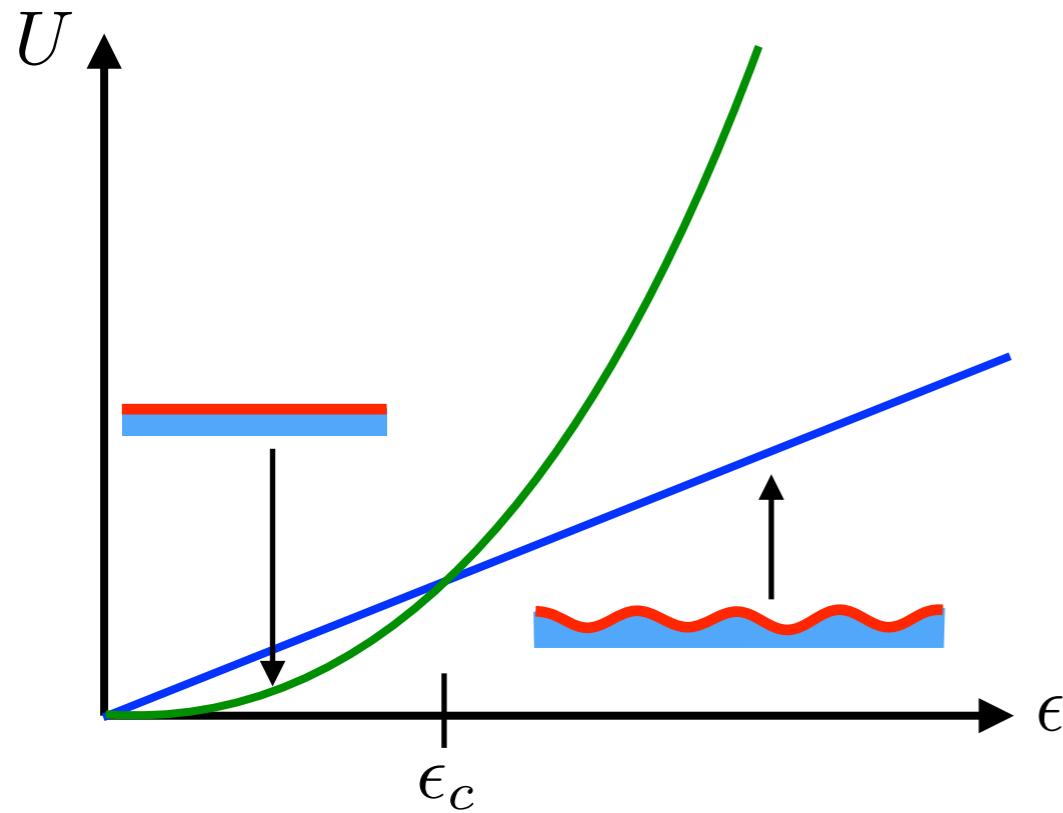
wavelength of wrinkles
on soft elastic substrates

$$\lambda = 2\pi \left(\frac{3\kappa}{E_s} \right)^{1/3}$$



Compression of stiff thin sheets on liquid and soft elastic substrates

liquid substrate



wrinkles are
stable above the
critical strain

$$\epsilon > \epsilon_c \sim \sqrt{\frac{\rho g d}{E_m}}$$

wavelength of
wrinkles

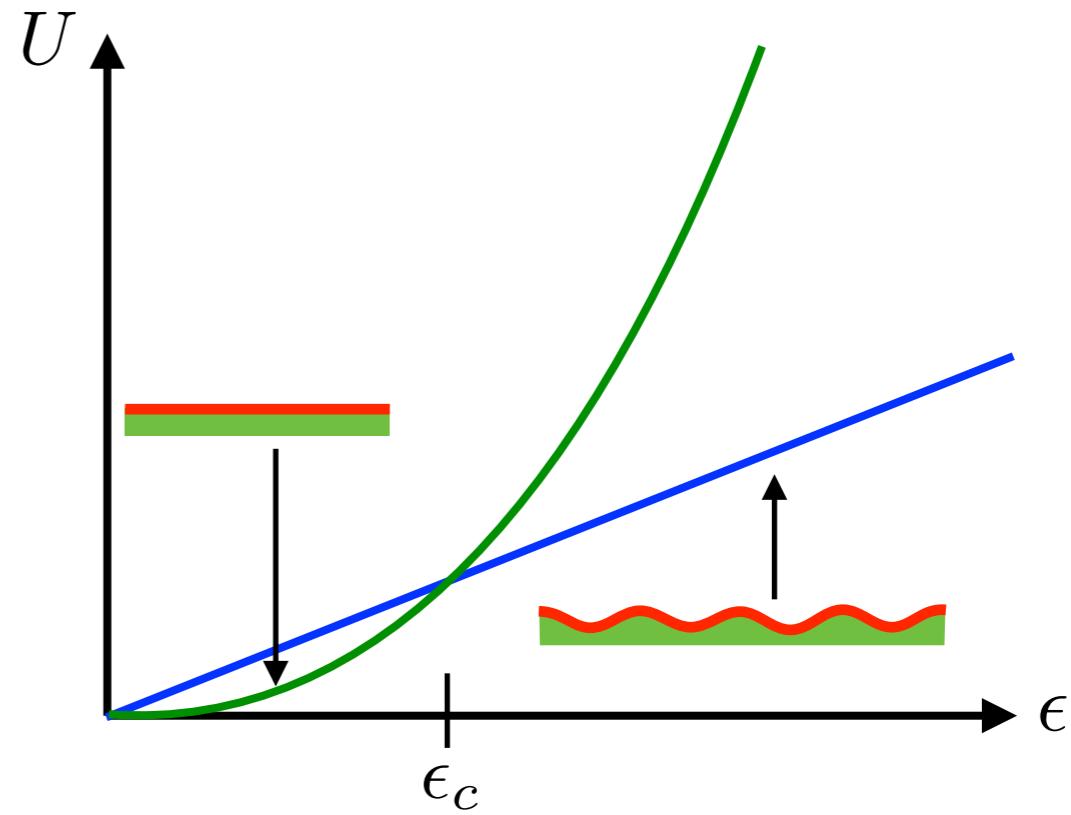
$$\lambda \sim \left(\frac{E_m d^3}{\rho g} \right)^{1/4}$$

amplitude of
wrinkles

$$h_0 \sim \lambda \sqrt{\epsilon}$$

soft elastic substrate

$E_s \ll E_m$



wrinkles are
stable for
large strains

$$\epsilon > \epsilon_c \sim \left(\frac{E_s}{E_m} \right)^{2/3}$$

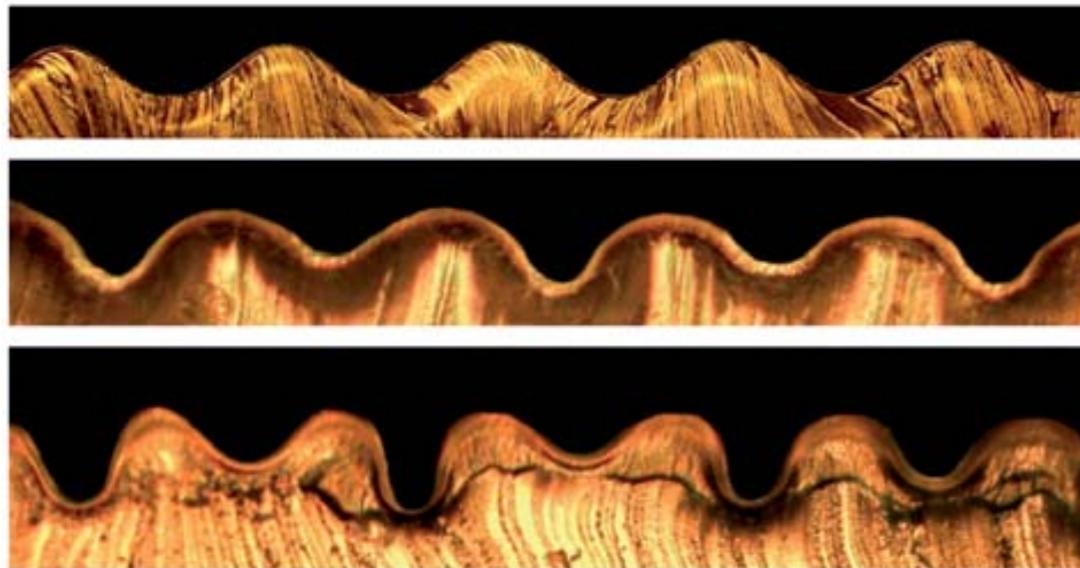
wavelength of
wrinkles

$$\lambda \sim d \left(\frac{E_m}{E_s} \right)^{1/3}$$

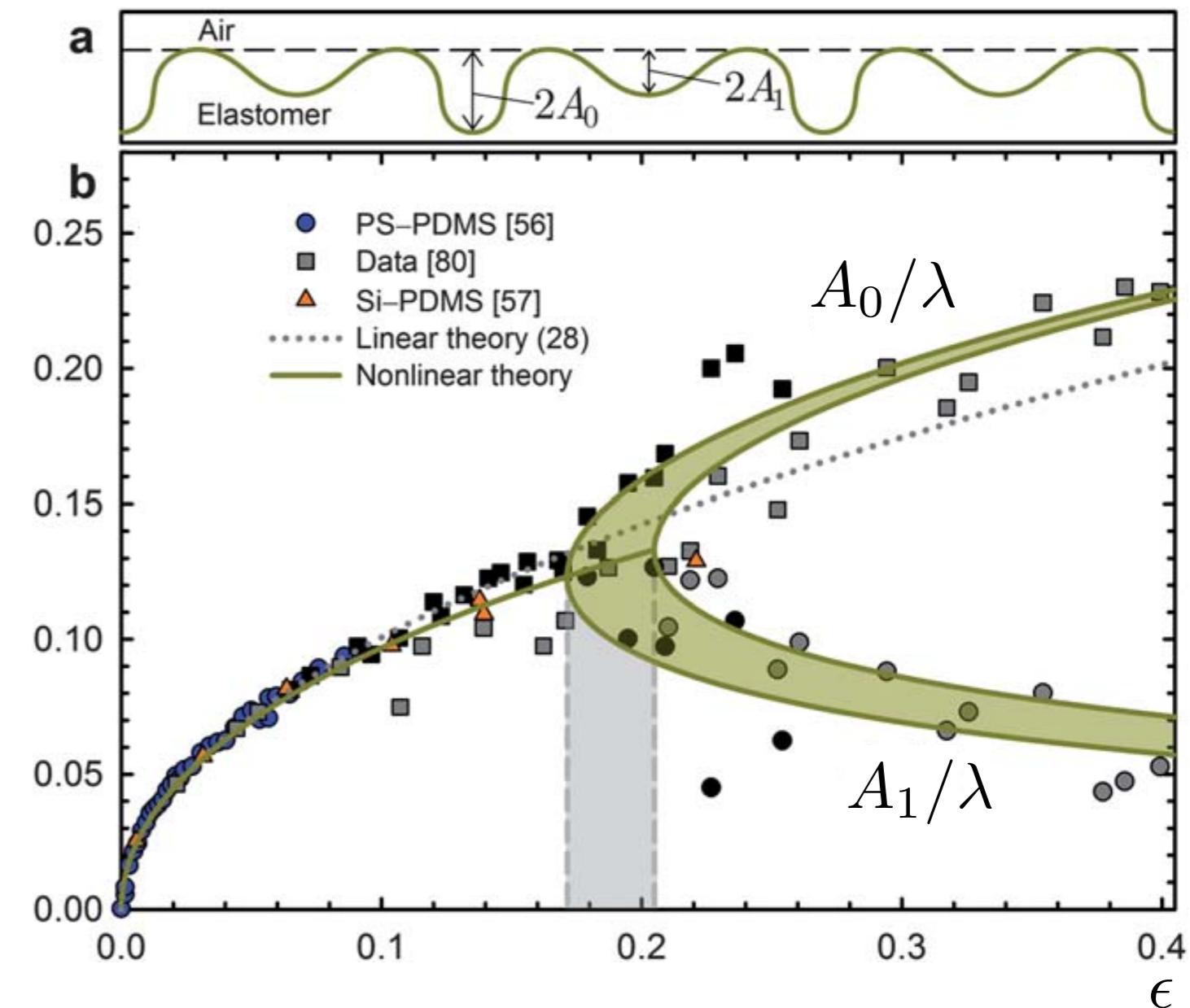
amplitude of
wrinkles

$$h_0 \sim \lambda \sqrt{\epsilon}$$

Compression of stiff thin membranes on soft elastic substrates



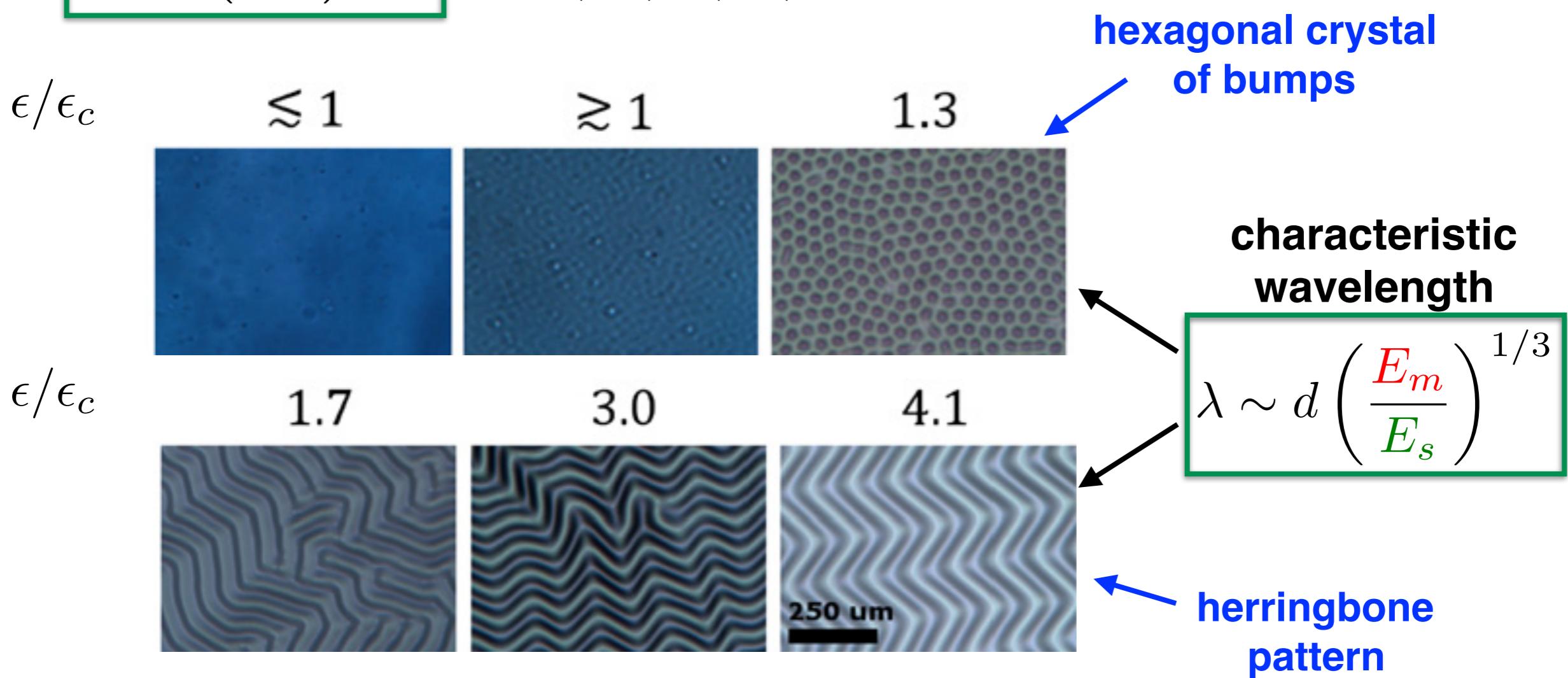
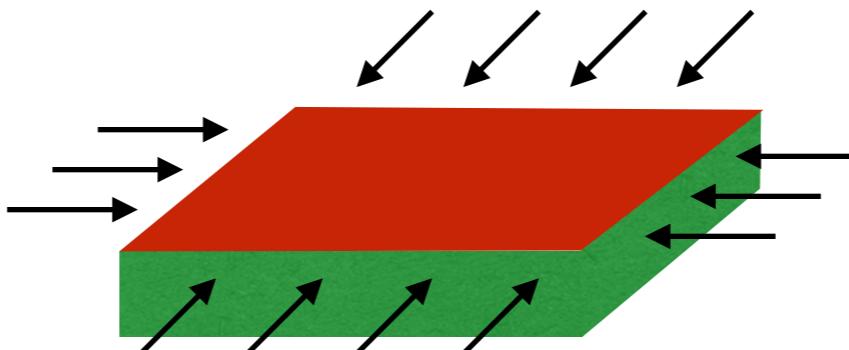
In order to explain period doubling (quadrupling, ...)
one has to take into account
the full nonlinear deformation
of the soft substrate!



Uniform compression of stiff thin membranes on soft elastic substrates

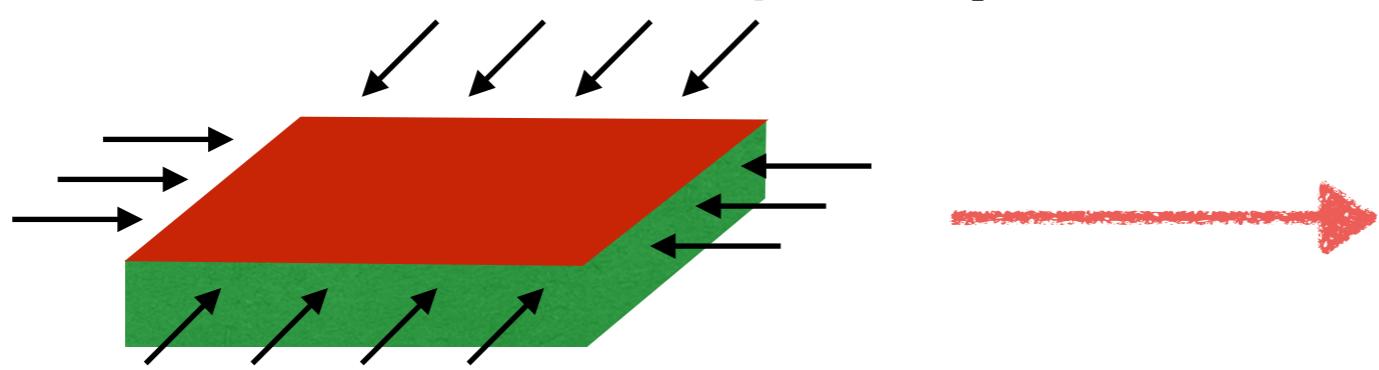
critical strain

$$\epsilon_c \sim \left(\frac{E_s}{E_m} \right)^{2/3}$$



Experimental protocols

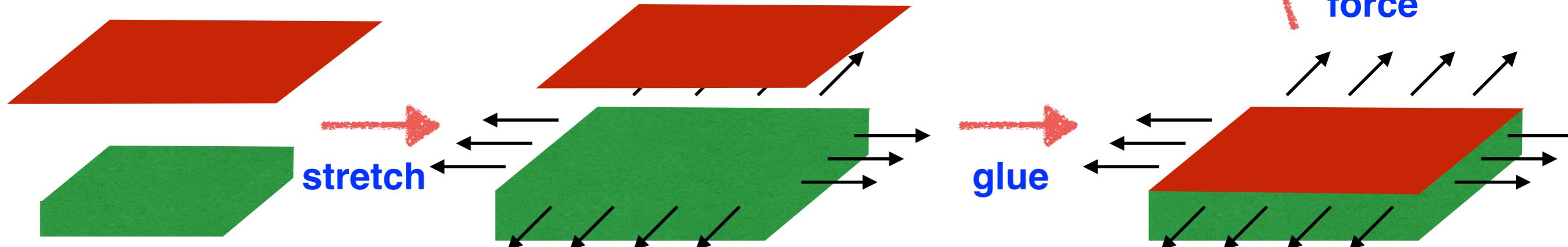
1.) compression



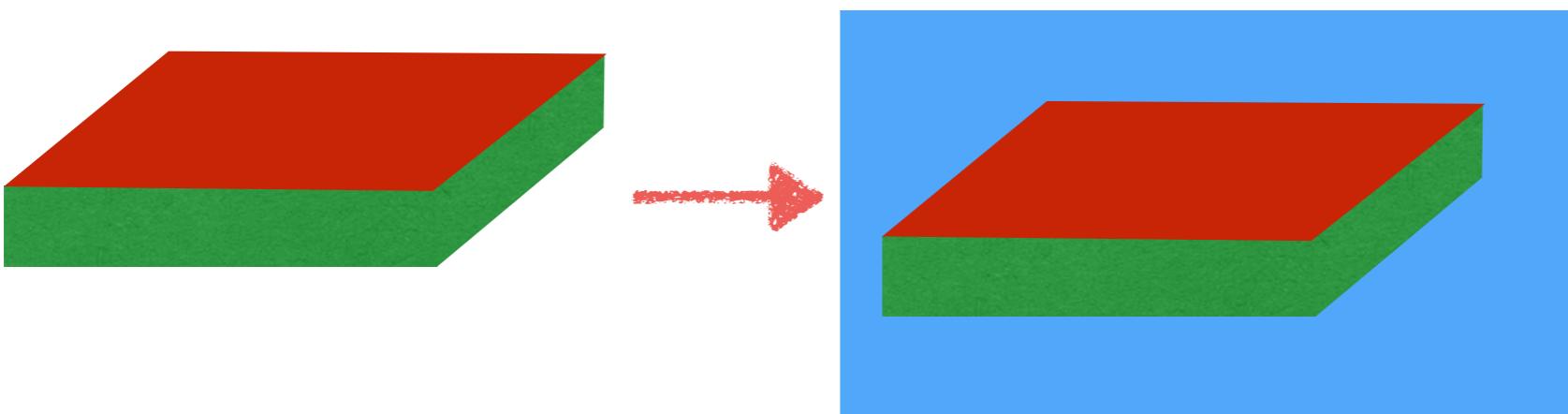
All protocols produce equivalent results for small strains!



2.) stretching and gluing



3.) differential swelling of gels

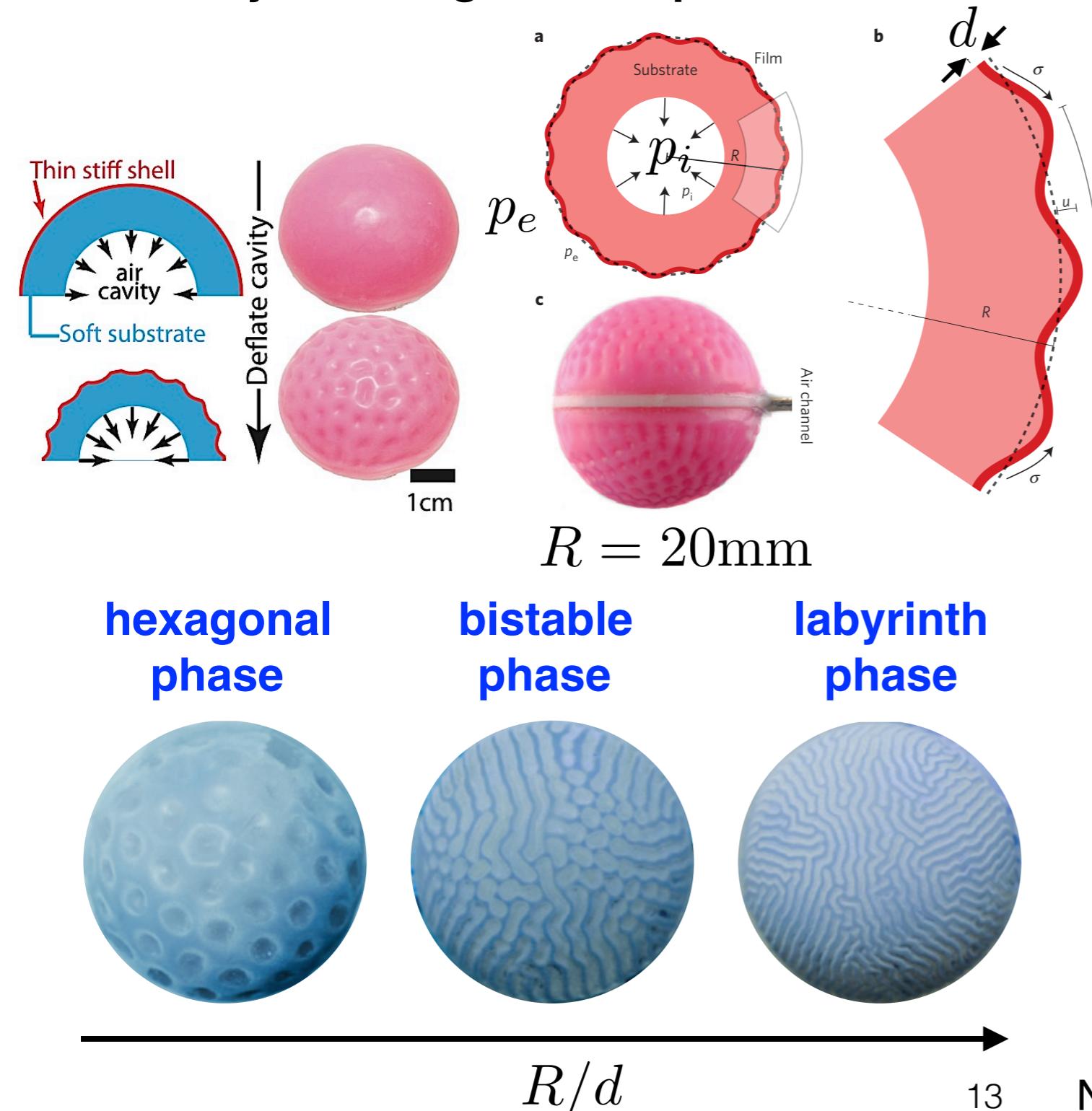


- 4.) differential growth in biology
- 5.) differential expansion due to temperature, electric field, etc.

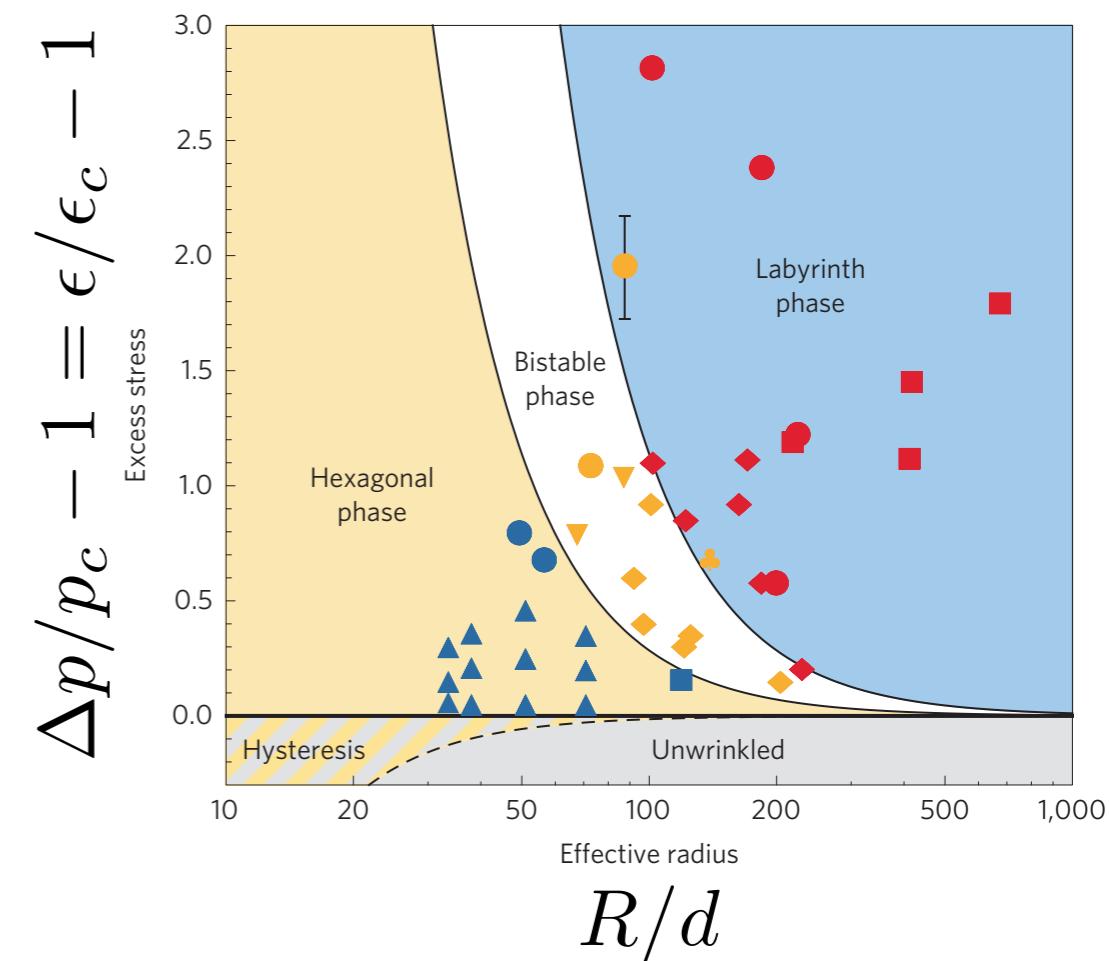
red gel swells more than the green gel

Compression of stiff thin membranes on a spherical soft substrates

Spherical shells are compressed
by reducing internal pressure



Phase diagram of
dimples/wrinkles

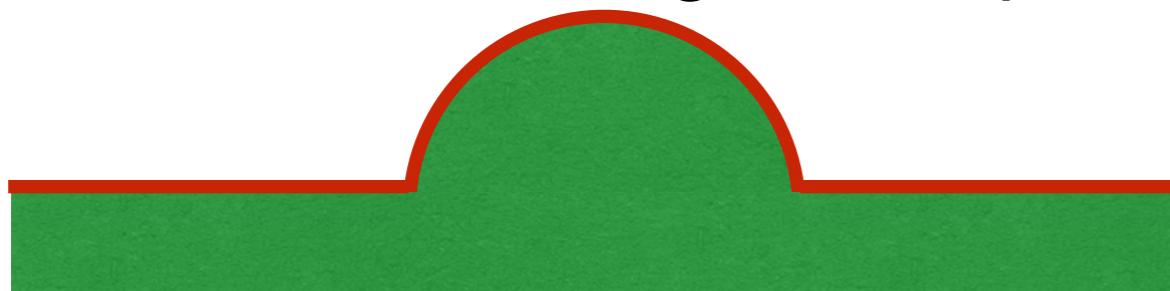


characteristic wavelength is
almost independent of radius R

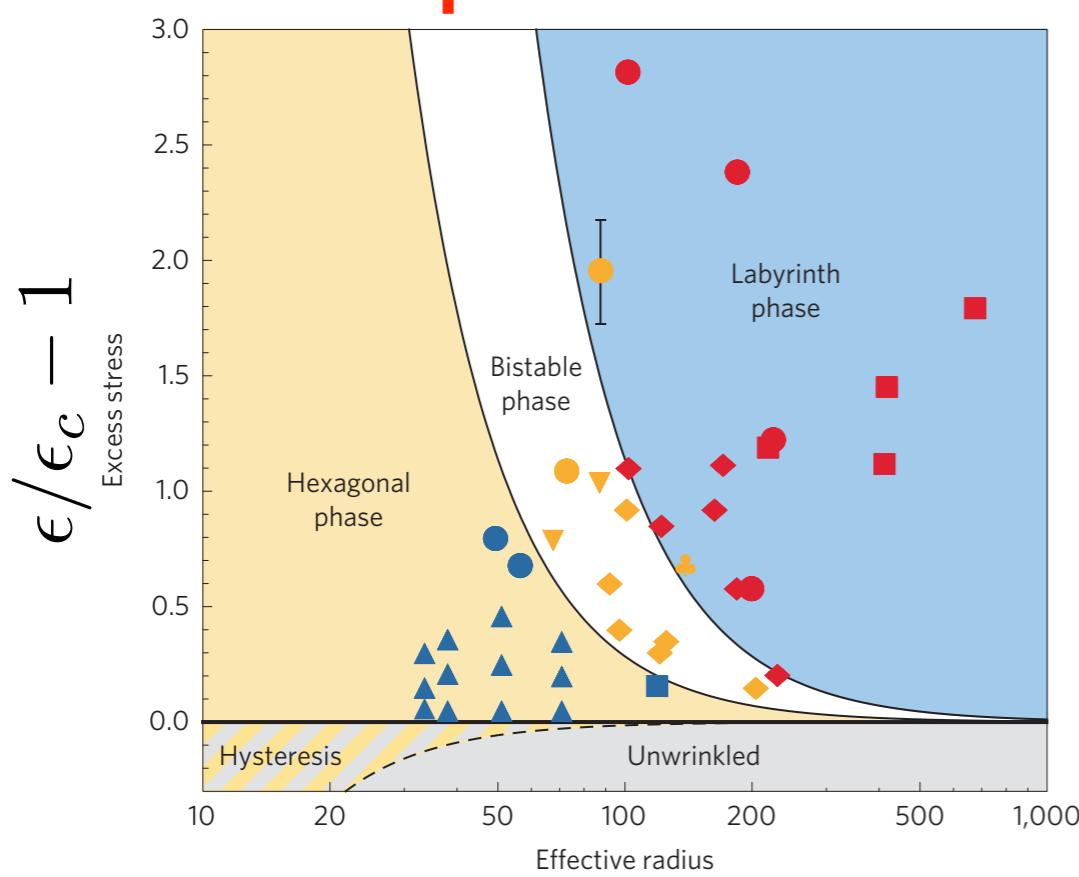
$$\lambda \sim d \left(\frac{E_m}{E_s} \right)^{1/3}$$

Compression of stiff thin membranes on a spherical soft substrates

Swelling of gels (red gel swells
more than the green one)

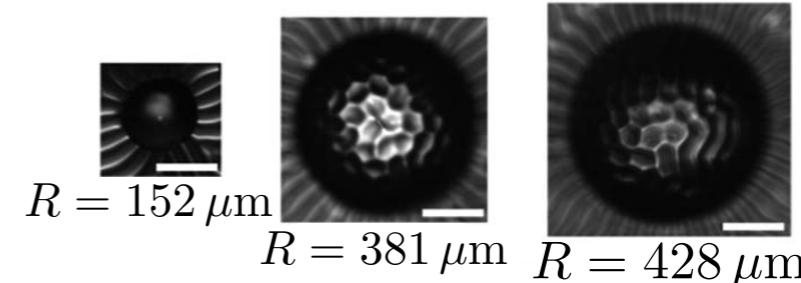


Phase diagram of
dimples/wrinkles



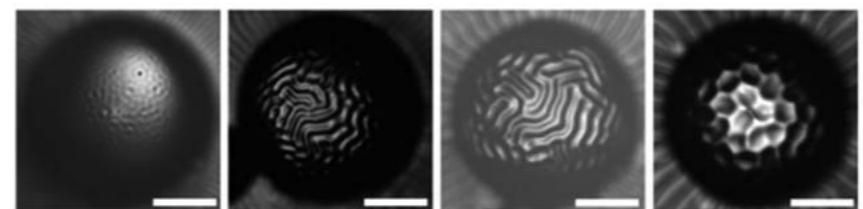
D. Breid and A.J. Crosby,
Soft Matter 9, 3624 (2013)

Modifying radius R
(fixed thickness d)



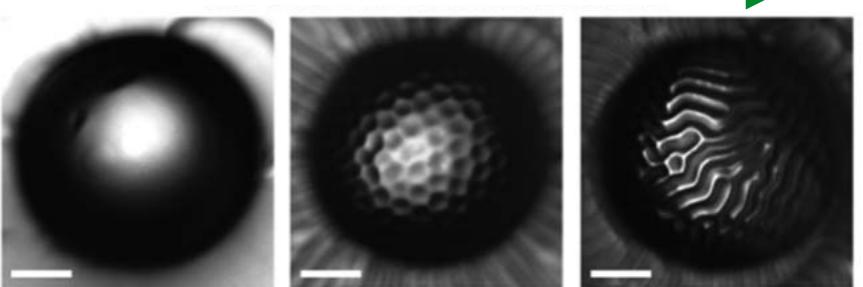
Modifying membrane thickness d

$R = 381 \mu\text{m}$

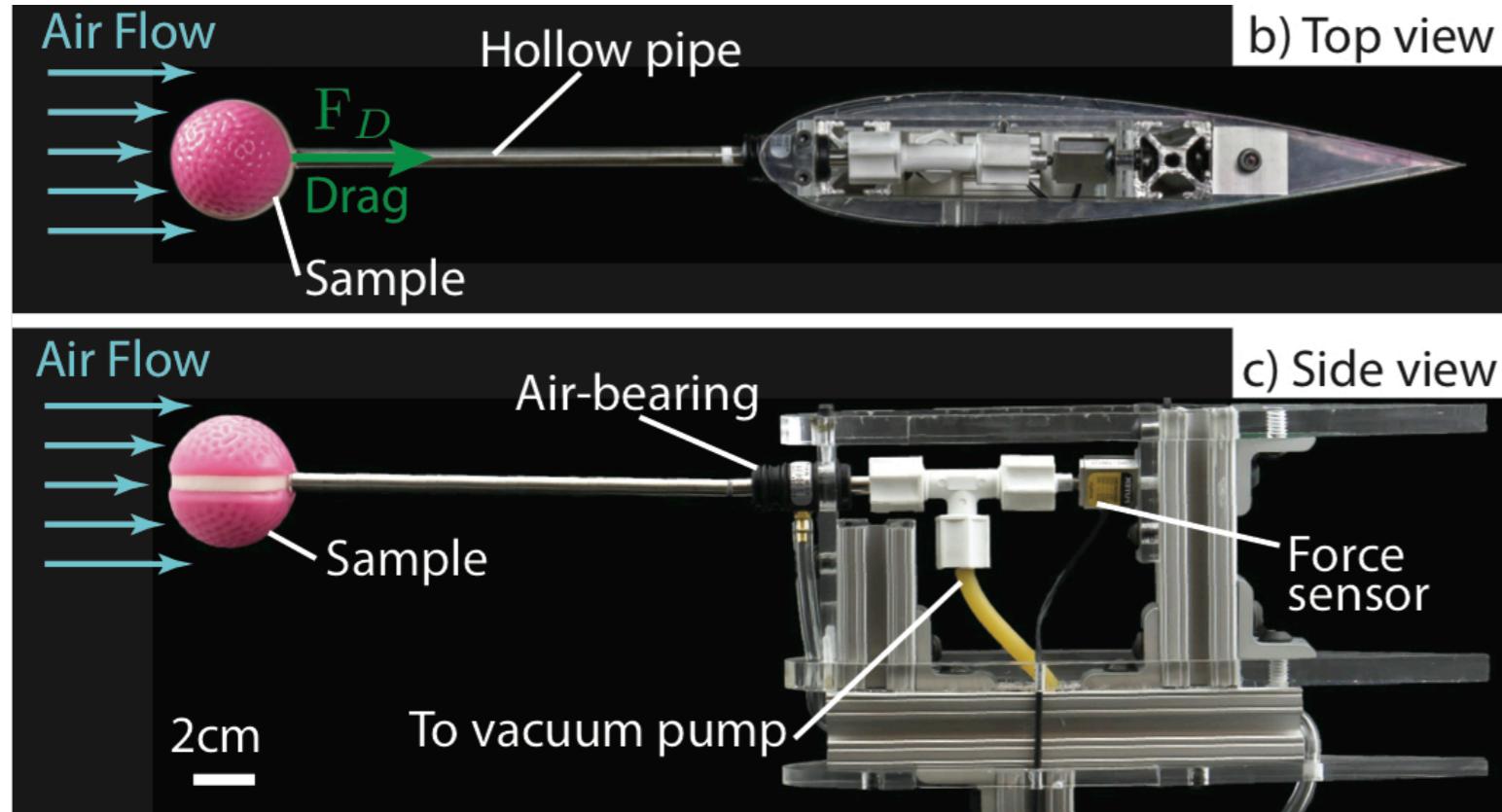


Modifying swelling strain ϵ

$R = 522 \mu\text{m}$



Tuning drag coefficient via wrinkling



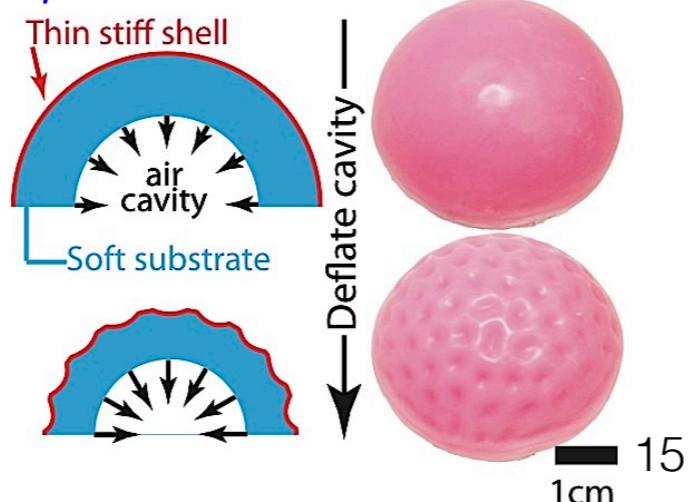
Drag Force

$$F_d = \frac{1}{2} C_D \rho u^2 A$$

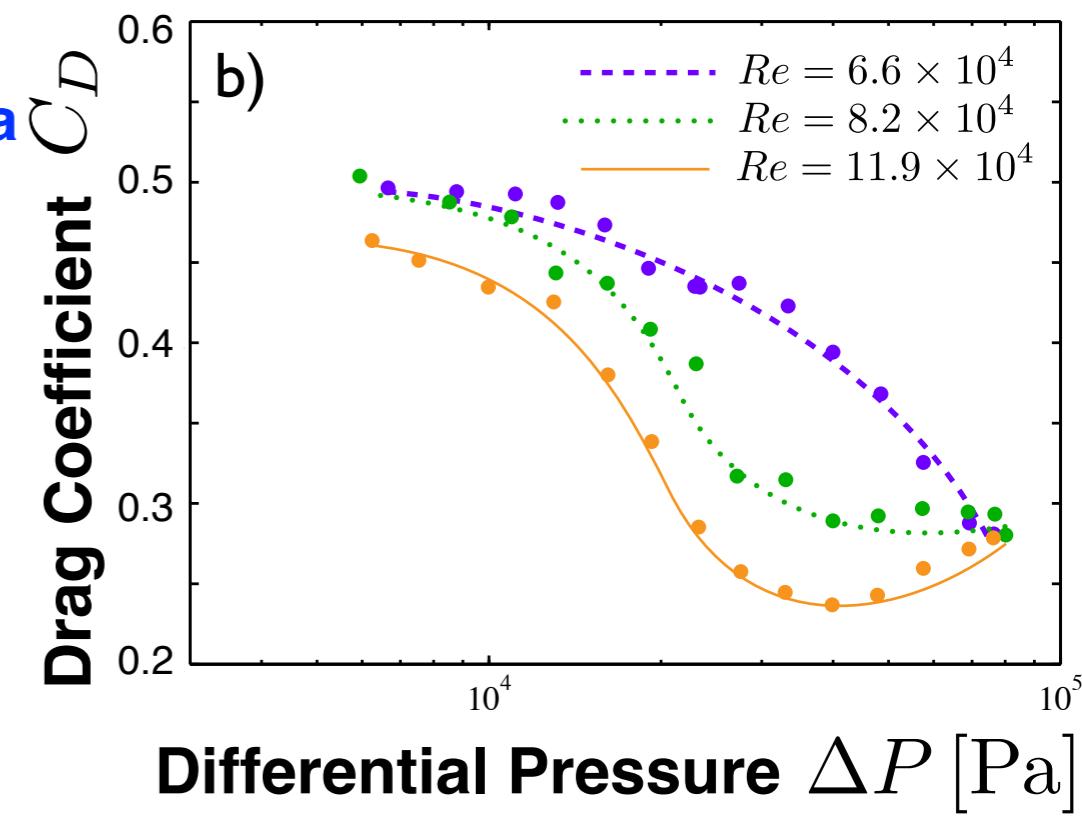
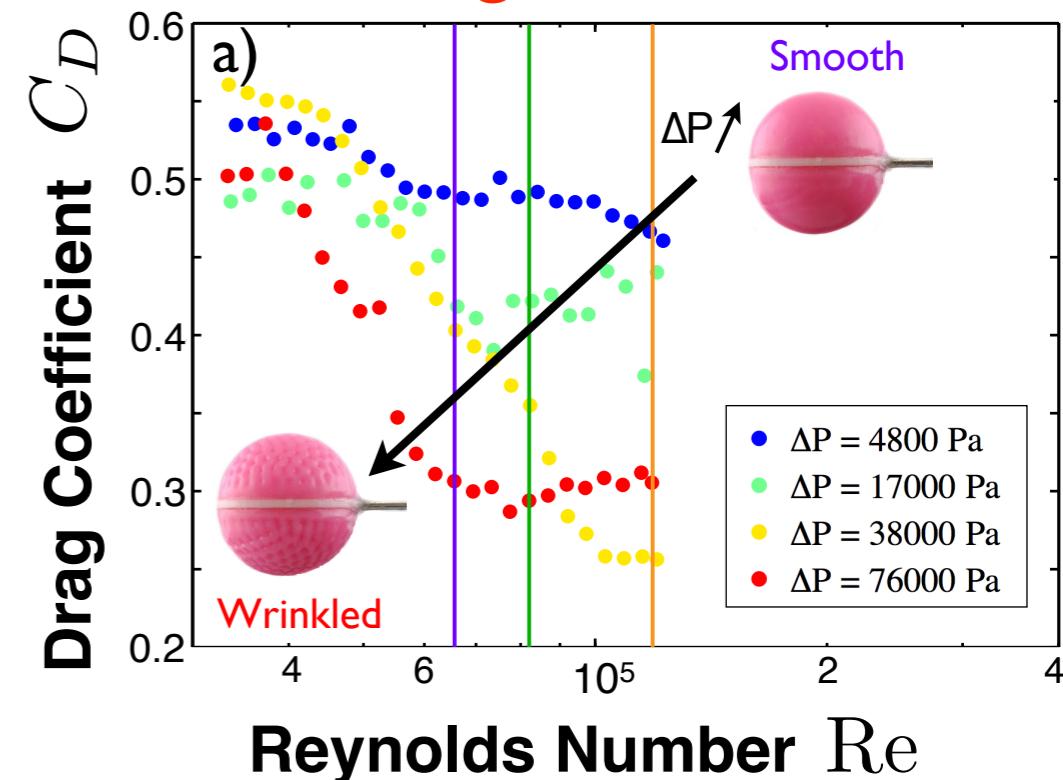
ρ air density
 u air flow speed
 R sphere radius
 $A = \pi R^2$ sphere cross-section area
 μ air viscosity

$$Re = \frac{\rho u (2R)}{\mu} \gg 1 \text{ Reynolds Number}$$

Depth of wrinkling is controlled via the reduction of internal pressure ΔP .

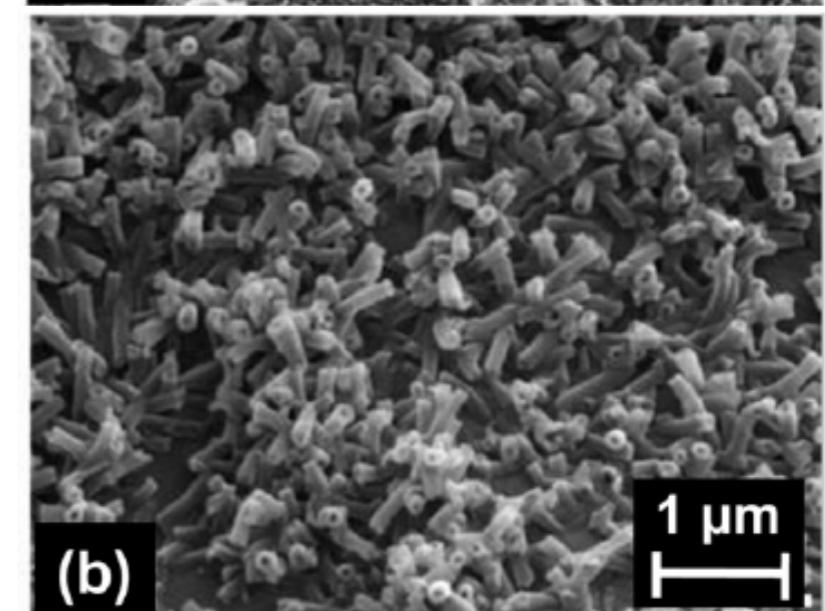
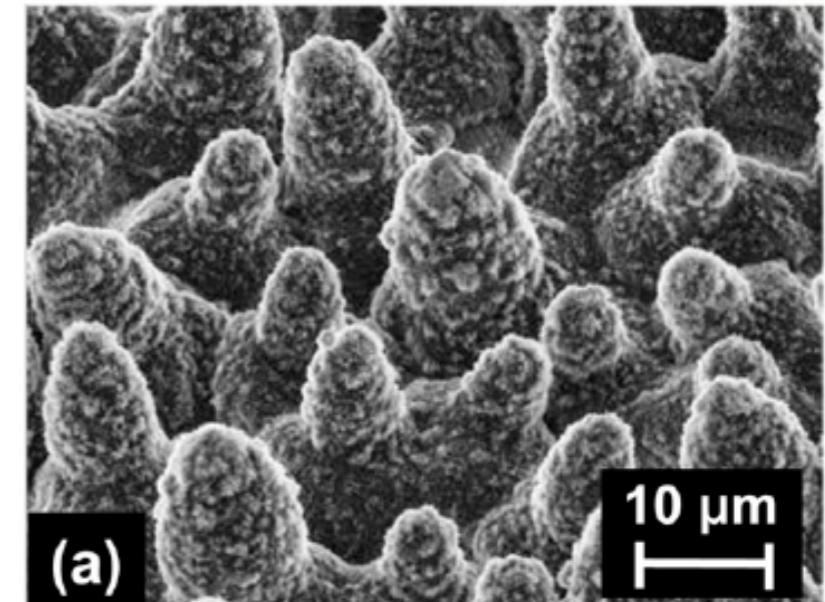


Wrinkling reduces drag coefficient



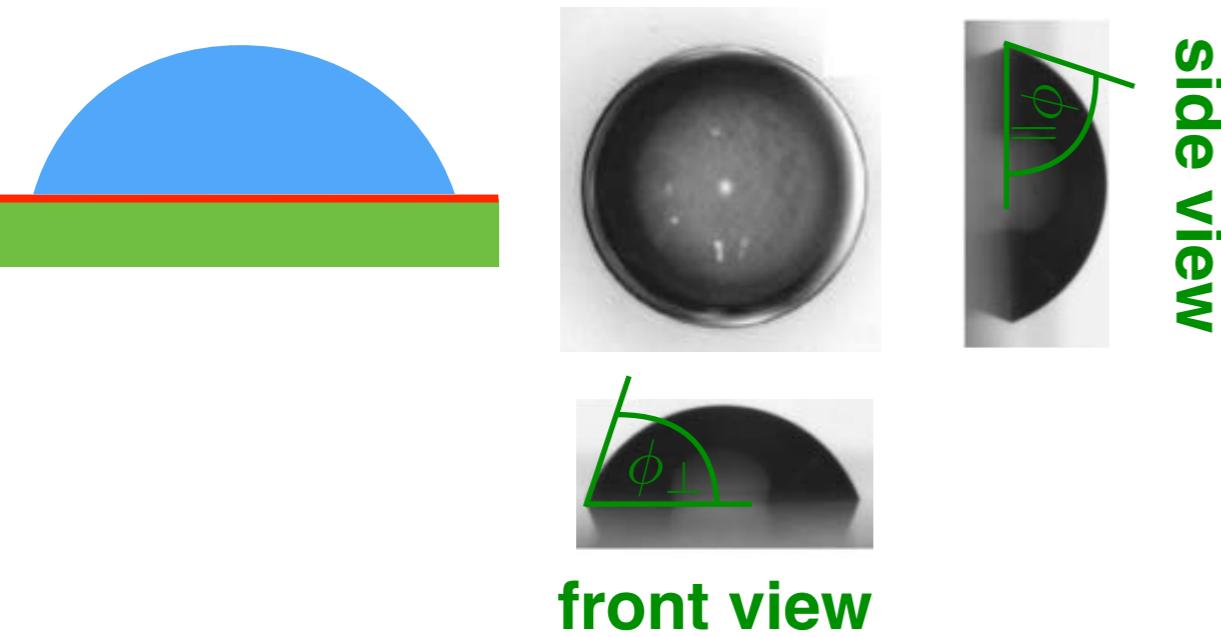
Self-cleaning property of lotus leaves

Lotus leaves repel water (hydrophobicity)
due to the rough periodic microstructure

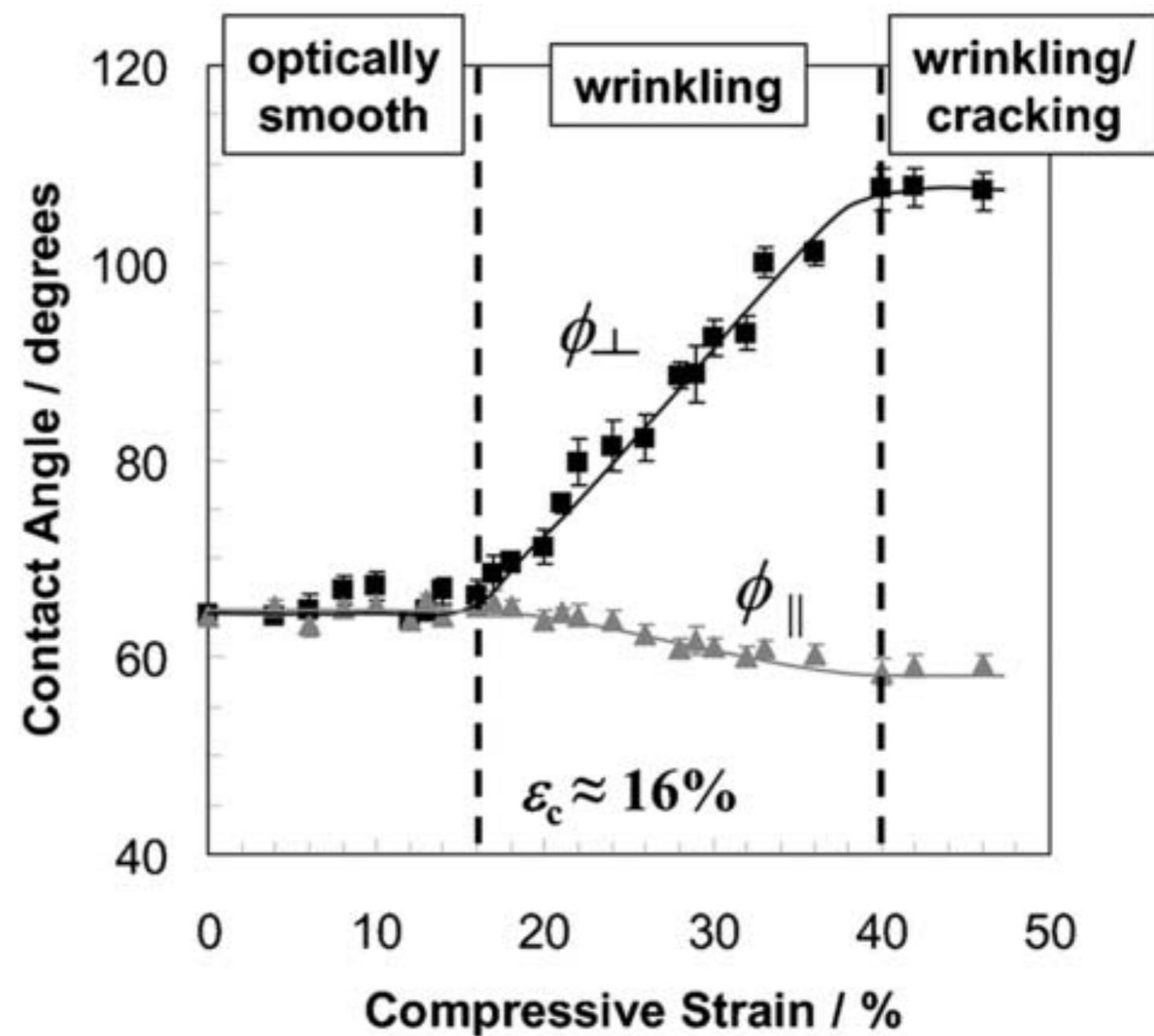
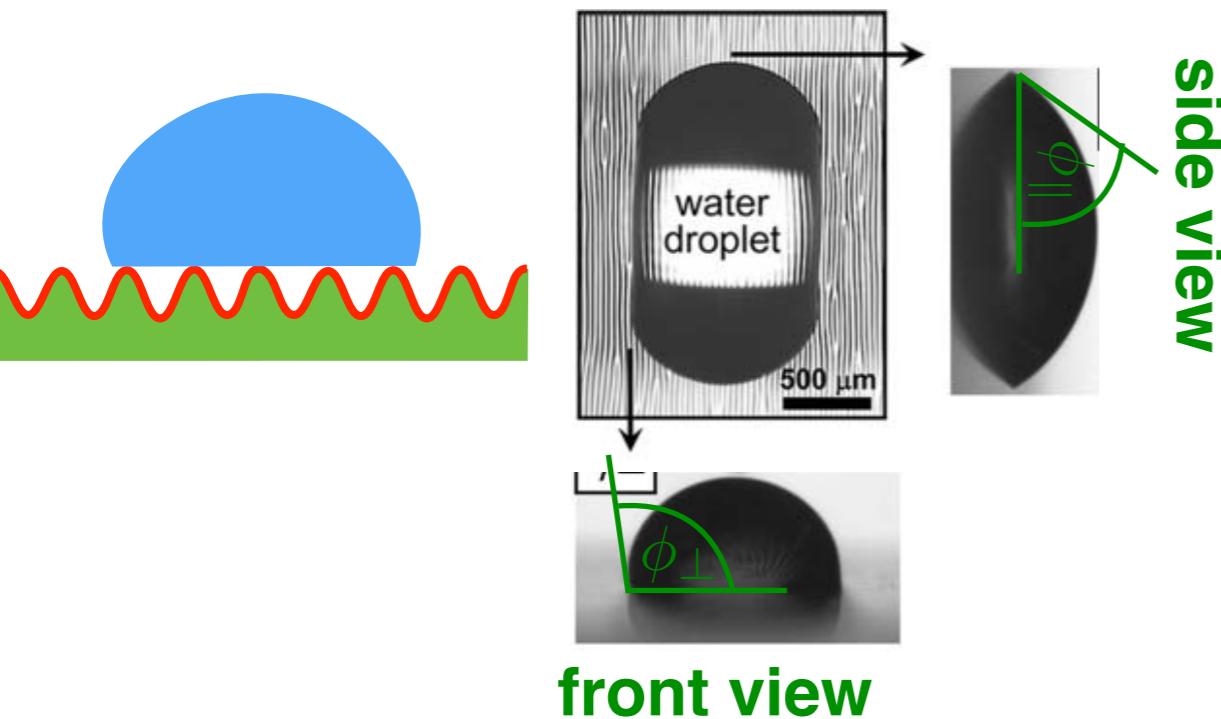


Tuning wetting angle via wrinkling

Water droplet on a flat surface



Water droplet on a wrinkled surface (wrinkling increases contact angle)

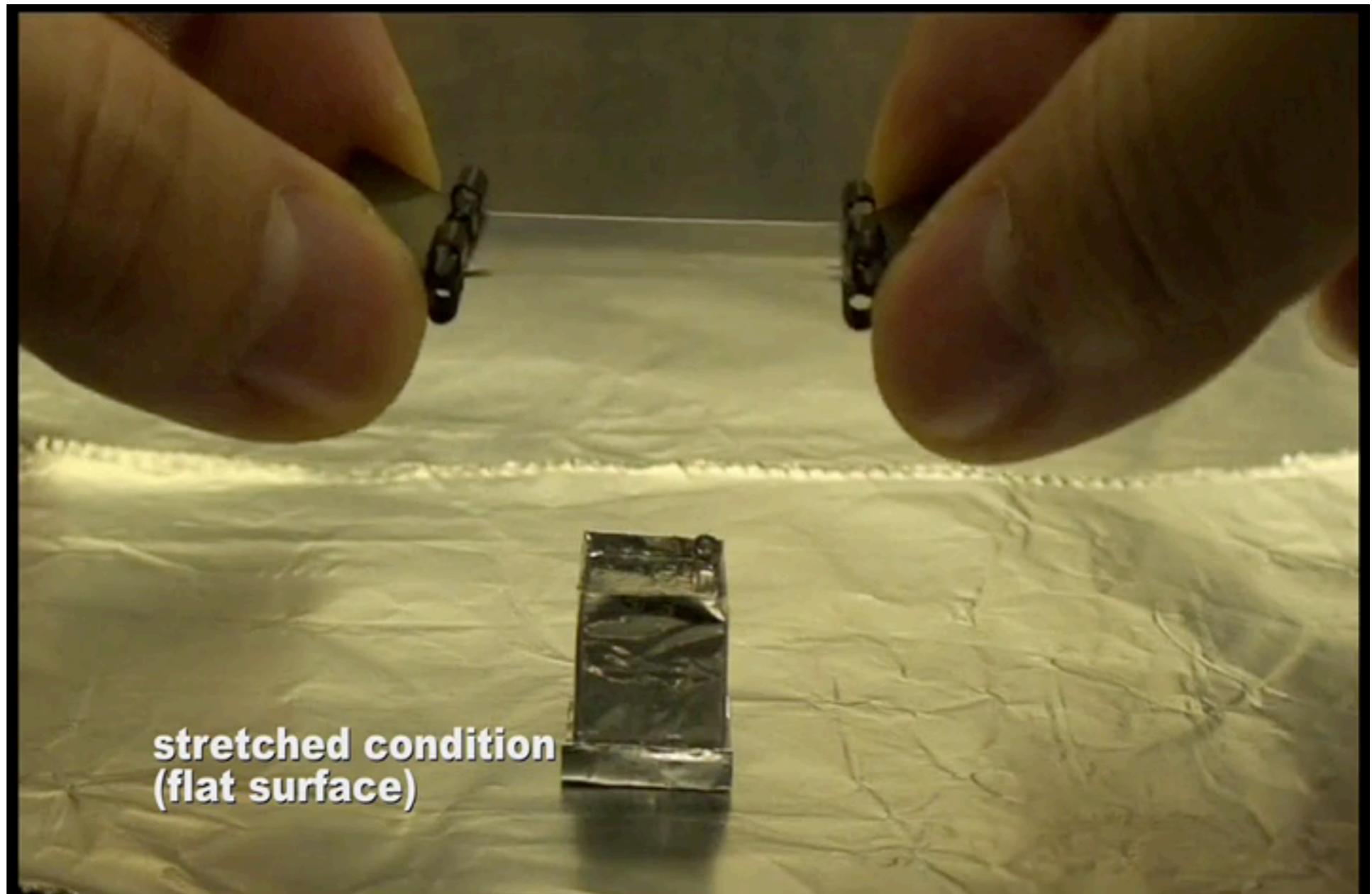
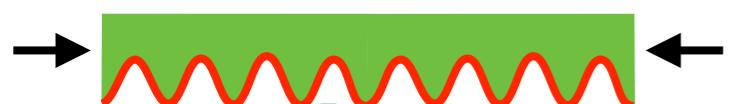


Tuning adhesion via wrinkling

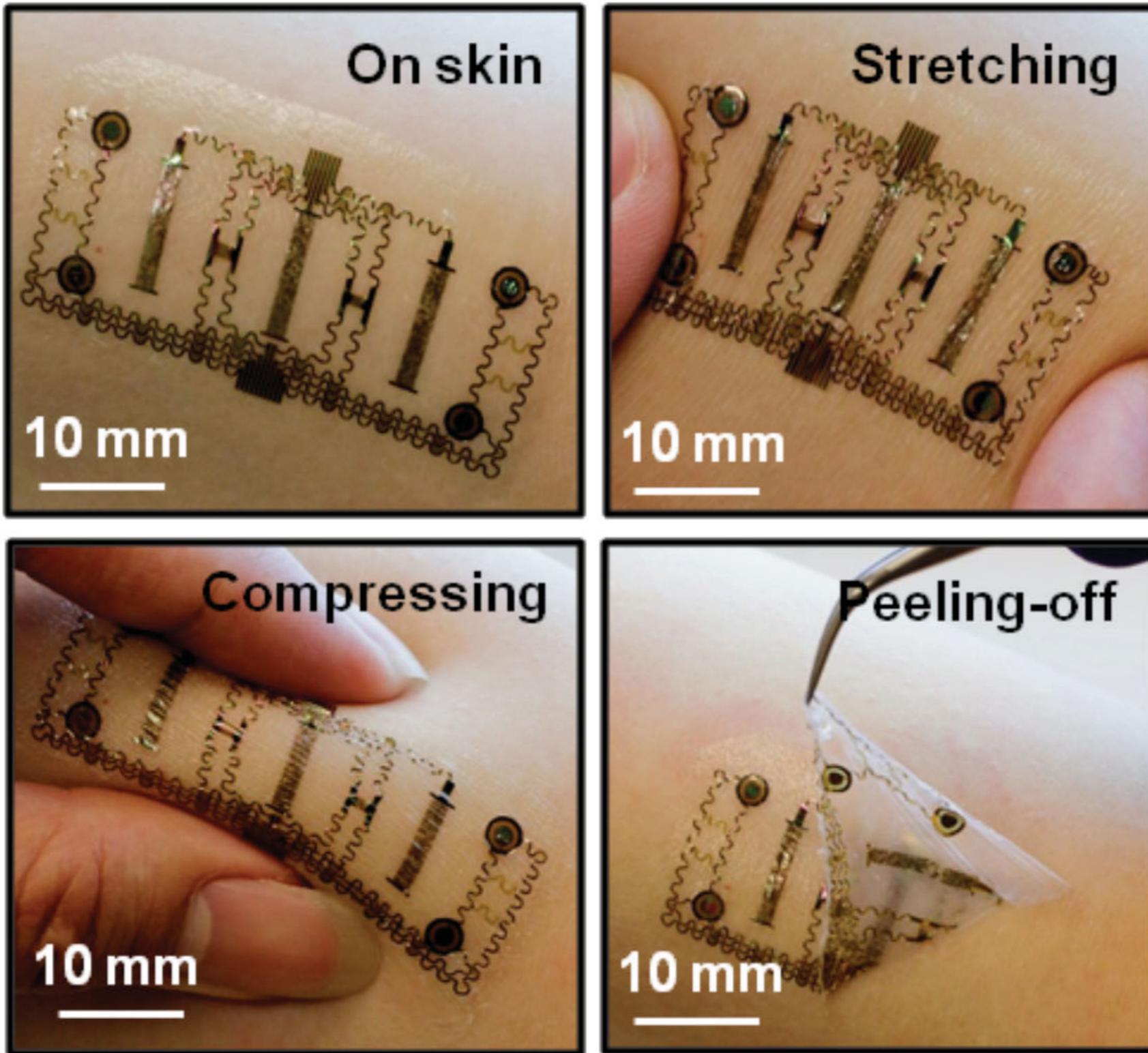
Flat compliant
surface has
enhanced adhesion
(larger contact area)



Wrinkling reduces
adhesion
(smaller contact area)

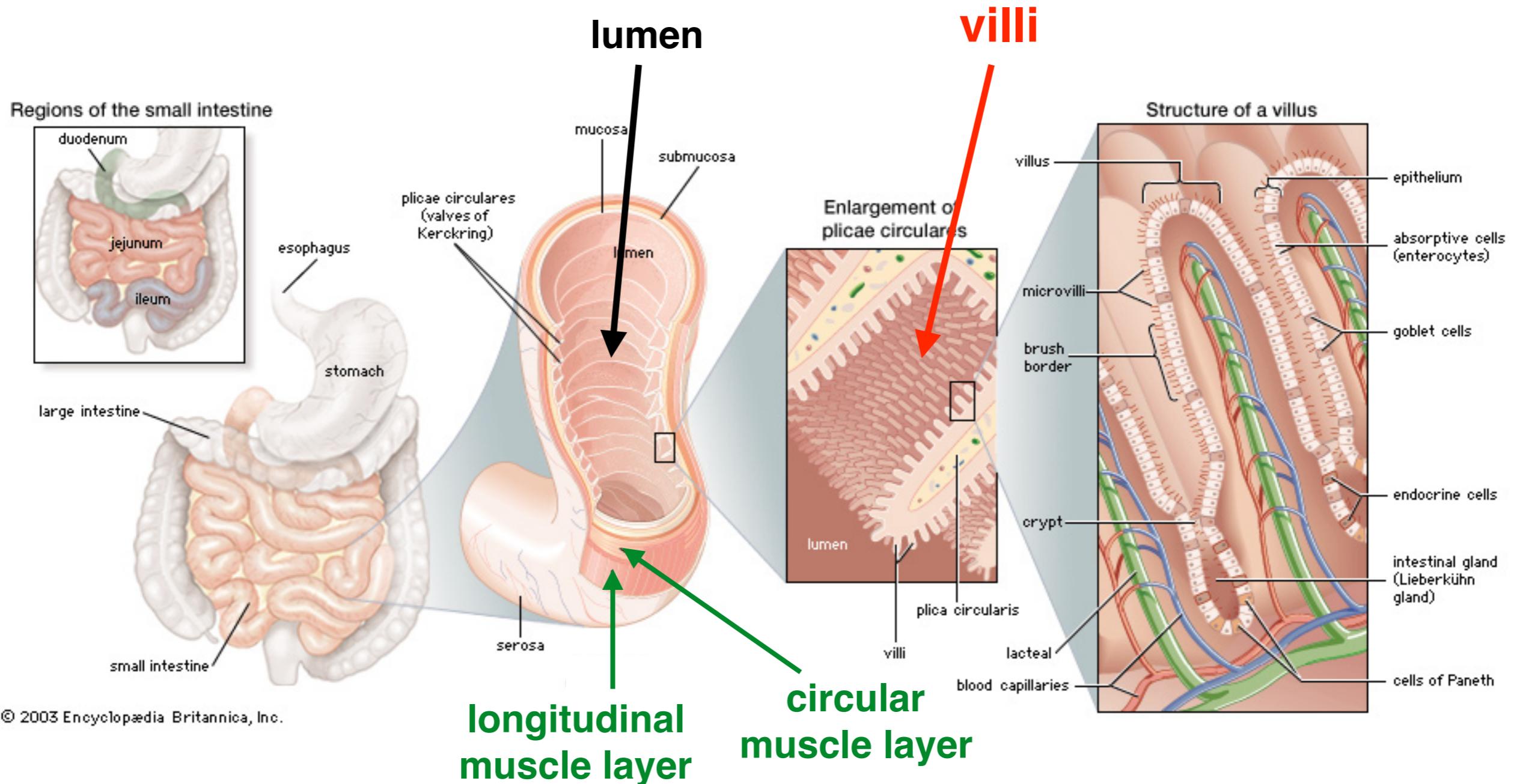


Wrinkled structures can be used for flexible electronics



B. Xu et al., *Adv. Mater.* **28**, 4462 (2016)

How are villi formed in guts?



Villi increase internal surface area of intestine for faster absorption of digested nutrients.

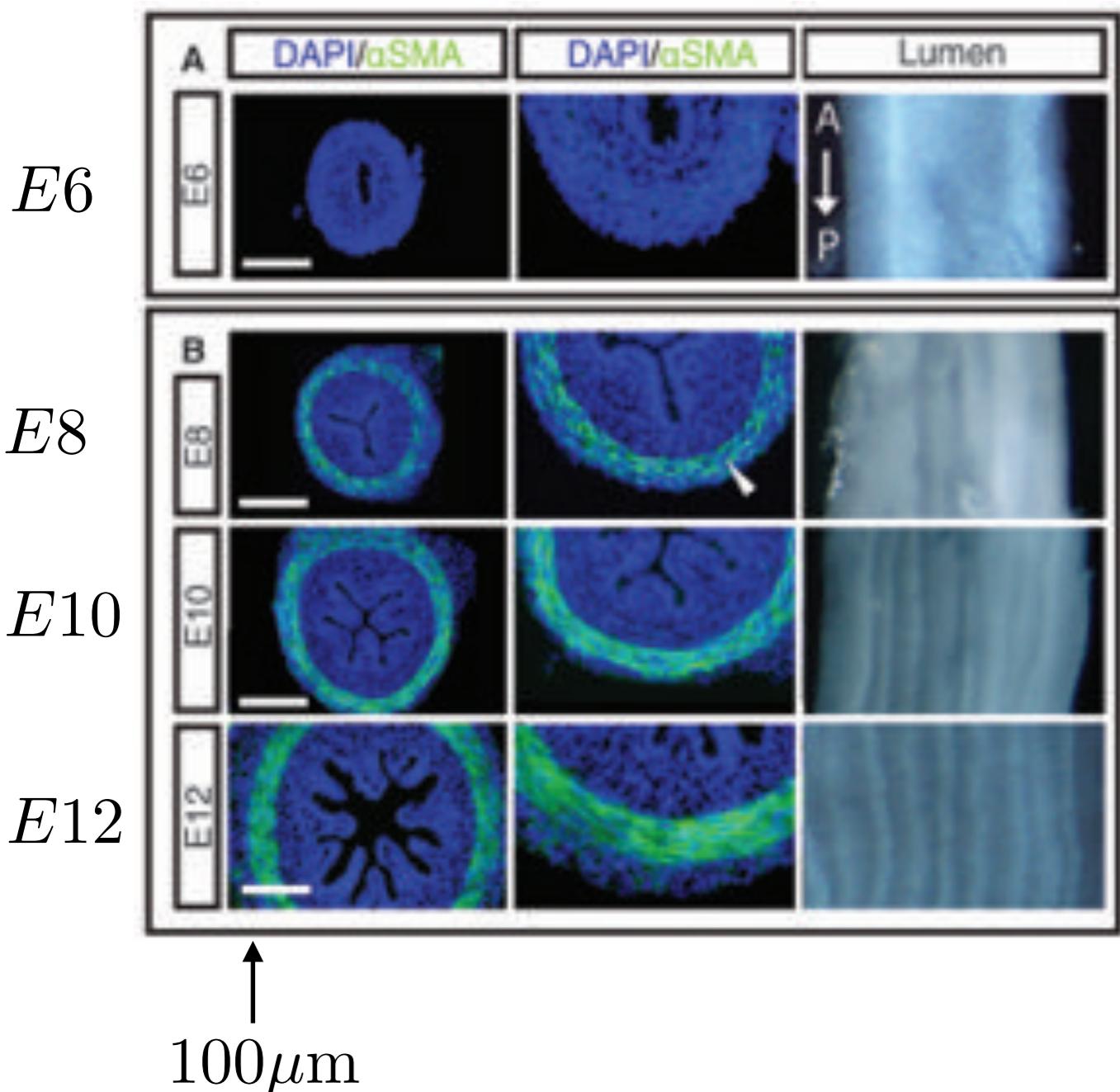
Lumen patterns in chick embryo



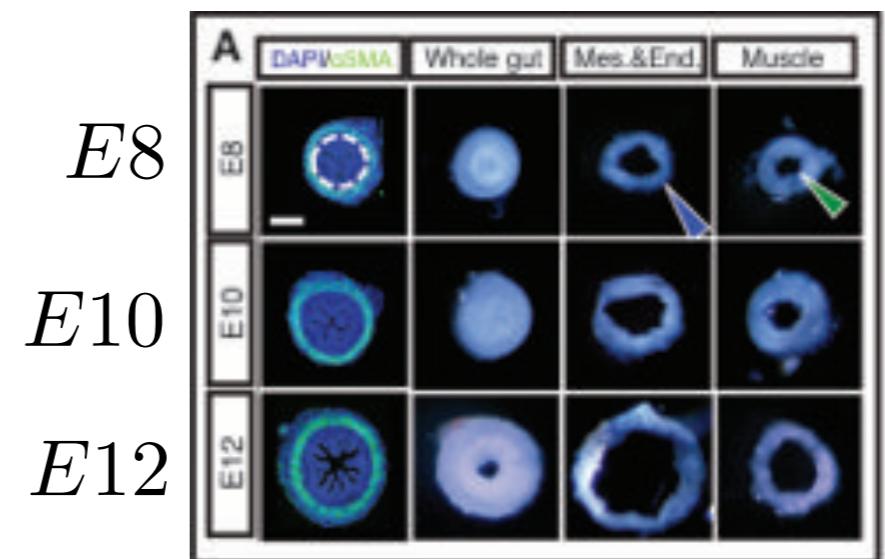
DAPI marks cell nuclei

aSMA marks smooth muscle actin

E...: age of chick embryo in days

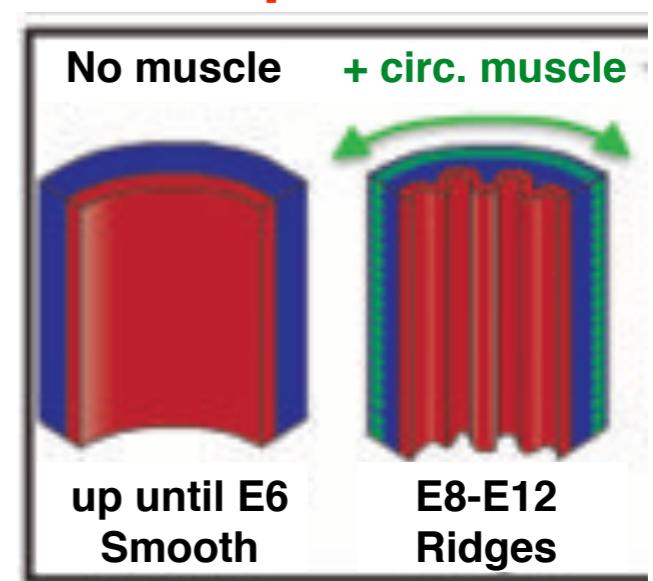


Stiff muscles grow slower than softer mesenchyme and endoderm layers

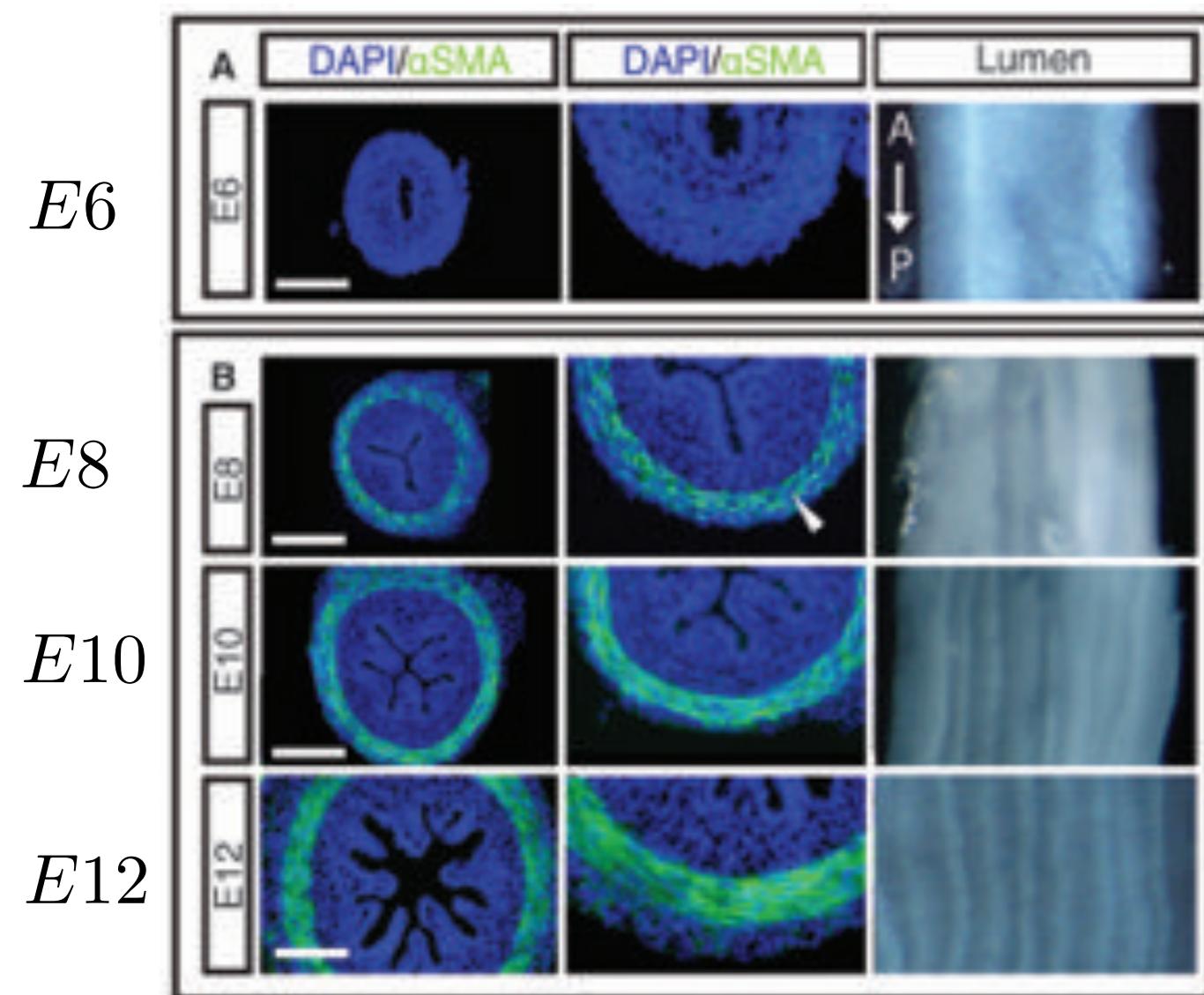


radial compression due to differential growth produces striped wrinkles

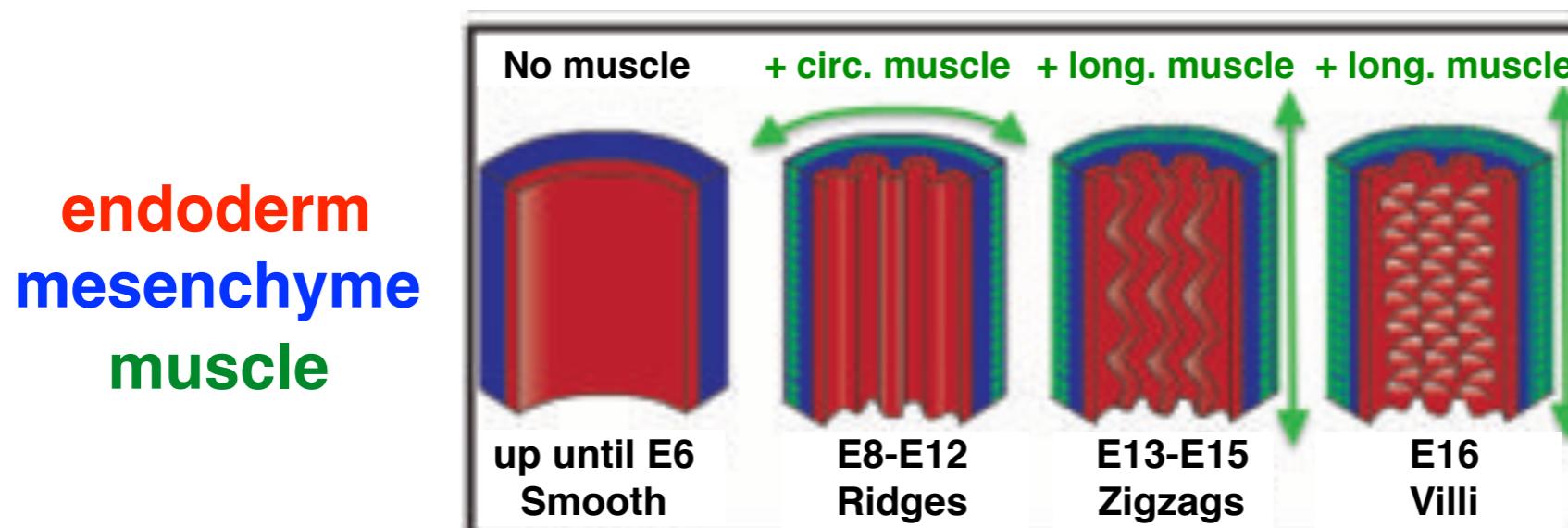
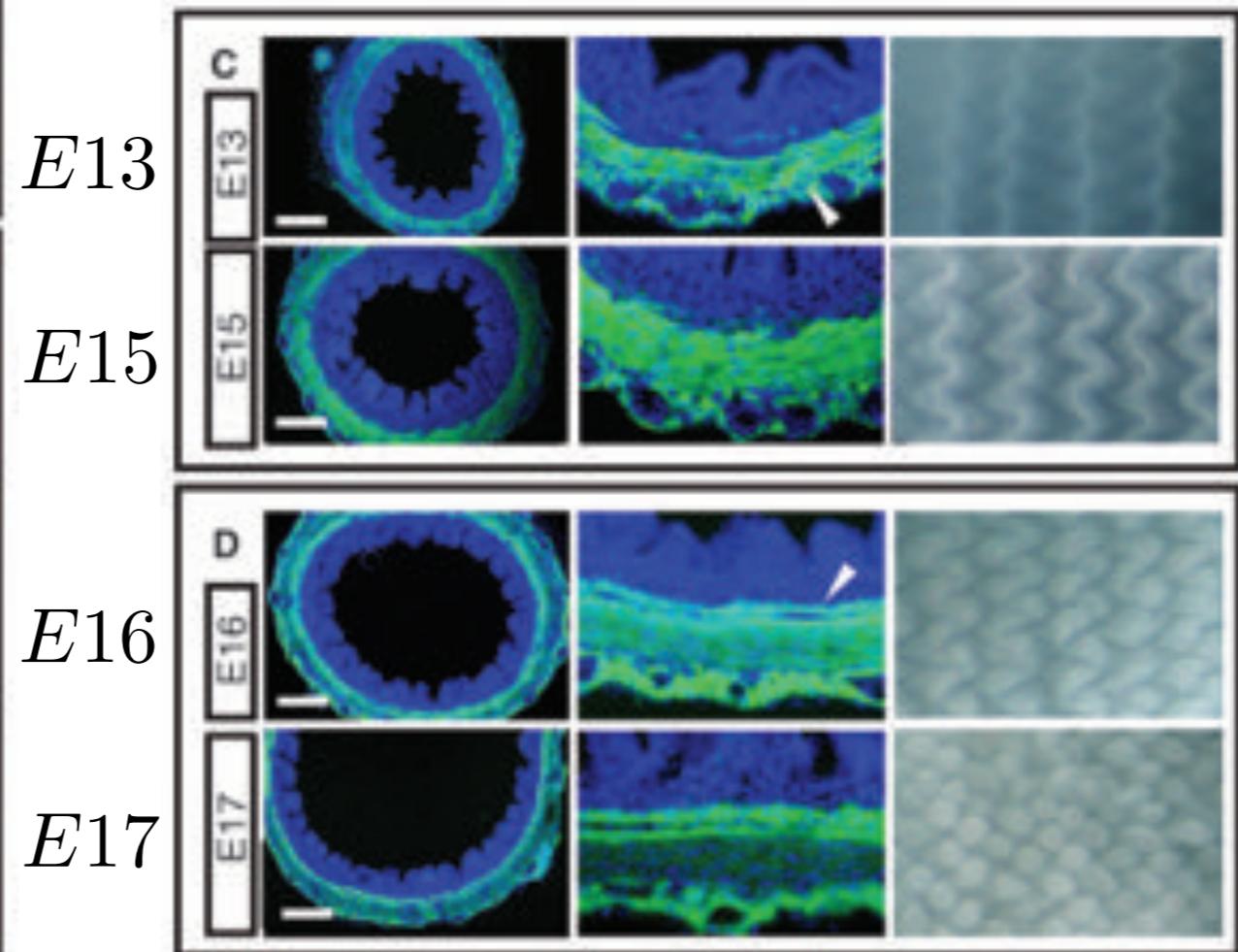
endoderm
mesenchyme
muscle



Lumen patterns in chick embryo

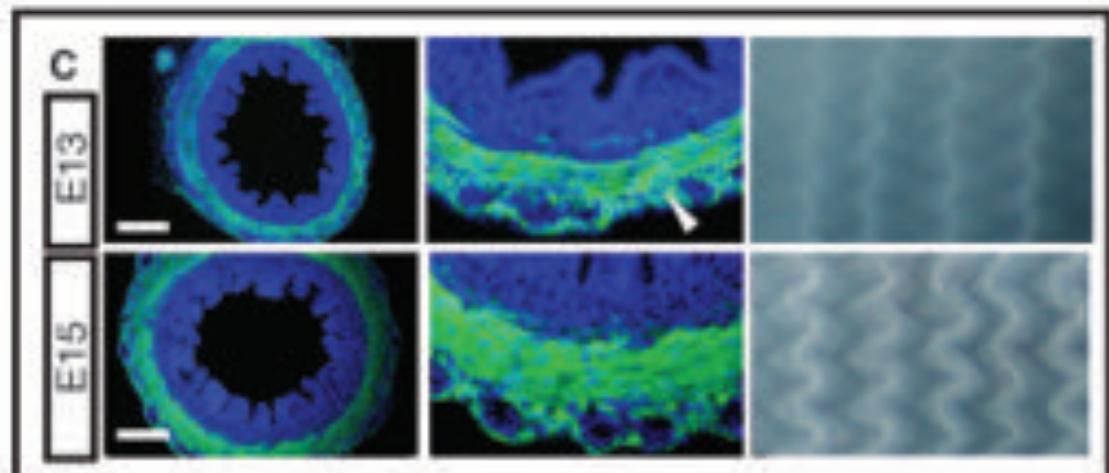


Formation of longitudinal muscles at E13 produces longitudinal compression

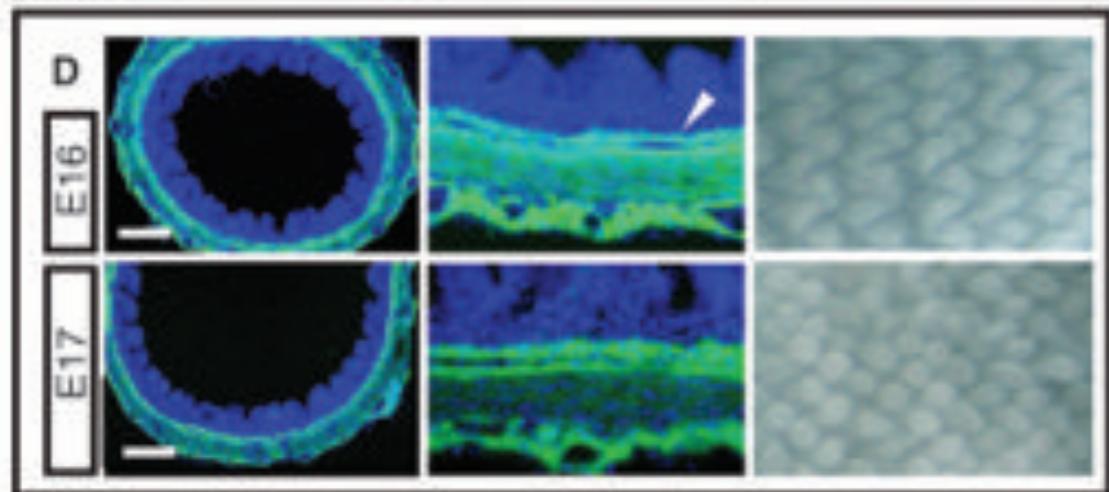


Lumen patterns in chick embryo

E13



E15



E16

Villi start forming at E16 because
of the faster growth in valleys

The same mechanism for
villi formation also works
in other organisms!

