MAE 545: Lecture 9 (3/1) Shapes of growing sheets

Reminder: no lectures next week

Metric tensor for measuring distances on surfaces

metric tensor for measuring lengths

$$
d\ell^2 = d\vec{r}^2 = \sum_{i,j} \vec{t}_i \cdot \vec{t}_j dx^i dx^j = \sum_{i,j} g_{ij} dx^i dx^j
$$

$$
g_{ij} = \vec{t}_i \cdot \vec{t}_j = \begin{pmatrix} \vec{t}_1 \cdot \vec{t}_1, & \vec{t}_1 \cdot \vec{t}_2 \\ \vec{t}_2 \cdot \vec{t}_1 & \vec{t}_2 \cdot \vec{t}_2 \end{pmatrix}
$$

$$
g = \det(g_{ij}) = |\vec{t}_1 \times \vec{t}_2|^2
$$

area element

$$
dA = |\vec{t_1}||\vec{t_2}| \sin \alpha dx^1 dx^2
$$

$$
dA = \sqrt{g} \, dx^1 dx^2
$$

Strain tensor and energy of shell deformations

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$$
g_{ij} = \frac{\partial \vec{r}}{\partial x^i} \cdot \frac{\partial \vec{r}}{\partial x^j}
$$

$$
d\ell^2 = \sum_{i,j} g_{ij} dx^i dx^j
$$

strain tensor

$$
u_{ij} = \frac{1}{2} \sum_{k} (g^{-1})_{ik} (g'_{kj} - g_{kj})
$$

inverse metric tensor

$$
\sum_{k} (g^{-1})_{ik} g_{kj} = \sum_{k} g_{ik} (g^{-1})_{kj} = \delta_{ij}
$$

Curvature of curves

Curvature tensor for surfaces

metric tensor for $g_{ij} = \vec{t}_i \cdot \vec{t}_j$ measuring lengths

curvature tensor for surfaces

$$
K_{ij} = \sum_{k} (g^{-1})_{ik} \left(\vec{n} \cdot \frac{\partial^2 \vec{r}}{\partial x^k \partial x^j} \right)
$$

principal curvatures correspond to the eigenvalues of curvature tensor

mean curvature

$$
\frac{1}{2}\left(\frac{1}{R_1} + \frac{1}{R_2}\right) = \frac{1}{2}\sum_i K_{ii} = \frac{1}{2}\text{tr}(K_{ij})
$$

Gaussian curvature

$$
\frac{1}{R_1 R_2} = \det(K_{ij})
$$

Surfaces of various principal curvatures

Examples for Gaussian curvature

$Examples$

 $\frac{\partial}{\partial x}$ = (1,0,0)

 $\frac{\partial^2 y}{\partial y} = (0, 1, 0)$

 $\vec{r}(x, y) = (x, y, 0)$

 $\partial \bar r$

 $\partial \bar r$

 $\vec{t}_x =$

 $\vec{t}_y =$

$$
K_{ij} = \sum_{k} (g^{-1})_{ik} \left(\vec{n} \cdot \frac{\partial^2 \vec{r}}{\partial x^k \partial x^j} \right)
$$

$$
g_{ij} = \vec{t}_i \cdot \vec{t}_j = \begin{pmatrix} 1, & 0 \\ 0, & 1 \end{pmatrix}
$$

$$
K_{ij} = \begin{pmatrix} 0, & 0 \\ 0, & 0 \end{pmatrix}
$$

$$
\frac{d}{dt}
$$

 \vec{t}_{θ}

 $\not\equiv$ *tx*

 $\bar{\mathcal{t}}$ *ty*

 \vec{n}

$$
\vec{n} = \frac{\vec{t}_x \times \vec{t}_y}{|\vec{t}_x \times \vec{t}_y|} = (0, 0, 1)
$$
\n
$$
\vec{r}(\phi, z) = (R \cos \phi, R \sin \phi, z)
$$
\n
$$
\vec{t}_\phi = \frac{\partial \vec{r}}{\partial \phi} = R(- \sin \phi, \cos \phi, 0)
$$
\n
$$
\vec{t}_z = \frac{\partial \vec{r}}{\partial z} = (0, 0, 1)
$$
\n
$$
\vec{n} = \frac{\vec{t}_\phi \times \vec{t}_z}{|\vec{t}_\phi \times \vec{t}_z|} = (\cos \phi, \sin \phi, 0)
$$
\n
$$
K_{ij} = \begin{pmatrix} -\frac{1}{R}, & 0\\ 0, & 0 \end{pmatrix}
$$

$$
\vec{r}(\theta,\phi) = R(\sin\theta\cos\phi, \sin\theta\sin\phi, \cos\theta) \n\vec{t}_{\phi} \quad \vec{t}_{\theta} = \frac{\partial\vec{r}}{\partial\theta} = R(\cos\theta\cos\phi, \cos\theta\sin\phi, -\sin\theta) \n\vec{n} \quad \vec{t}_{\phi} = \frac{\partial\vec{r}}{\partial\phi} = R\sin\theta(-\sin\phi, \cos\phi, 0) \n\vec{n} = \frac{\vec{t}_{\theta} \times \vec{t}_{\phi}}{|\vec{t}_{\theta} \times \vec{t}_{\phi}|} = (\sin\theta\cos\phi, \sin\theta\sin\phi, \cos\theta) \n\vec{n} = \frac{\vec{t}_{\theta} \times \vec{t}_{\phi}}{|\vec{t}_{\theta} \times \vec{t}_{\phi}|} = (\sin\theta\cos\phi, \sin\theta\sin\phi, \cos\theta)
$$

Bending energy for deformation of shells

undeformed shell deformed shell

$$
Poisson's ratio \nu
$$

$$
K_{ij} = \sum_{k} (g^{-1})_{ik} \left(\vec{n} \cdot \frac{\partial^2 \vec{r}}{\partial x^k \partial x^j} \right)
$$

$$
K'_{ij} = \sum_{k} (g'^{-1})_{ik} \left(\vec{n}' \cdot \frac{\partial^2 \vec{r}'}{\partial x^k \partial x^j} \right)
$$

bending strain tensor

$$
b_{ij}=K_{ij}^{\prime}-K_{ij}
$$

(local measure of deviation from preferred curvature)

Energy cost of bending

$$
U = \int (\sqrt{g} dx^{1} dx^{2}) \left[\frac{1}{2} \kappa (\text{tr}(b_{ij}))^{2} + \kappa_{G} \text{det}(b_{ij}) \right]
$$

$$
\kappa = \frac{Ed^3}{12(1-\nu^2)} \quad \kappa_G = -\frac{Ed^3}{12(1+\nu)}
$$

Bending strain for deformation of flat plates

undeformed plate deformed plate

local normal

$$
\vec{n} = \frac{\vec{t}_x \times \vec{t}_y}{|\vec{t}_x \times \vec{t}_y|} = \vec{e}_z
$$

$$
K_{ij} = \vec{n} \cdot \partial_i \partial_j \vec{r} = 0
$$

local normal (neglecting in-plane deformations)

$$
\vec{n'} \approx \frac{\vec{e_z} - (\partial_x h) \vec{e_x} - (\partial_y h) \vec{e_y}}{\sqrt{1 + (\partial_x h)^2 + (\partial_y h)^2}}
$$

reference curvature tensor bending strain tensor

$$
\vec{r} = 0 \qquad \qquad \boxed{b_{ij} = K'_{ij} \approx \partial_i \partial_j h + \cdots}
$$

Mechanics of growing sheets

Growth defines preferred metric tensor g_{ij} , and preferred curvature tensor K_{ij} .

The equilibrium membrane shape $\vec{r}^{\,\prime}(x^1,x^2)$ **corresponds to the minimum of elastic energy:**

$$
U = \int \left(\sqrt{g} dx^1 dx^2\right) \left[\frac{1}{2}\lambda \left(\sum_i u_{ii}\right)^2 + \mu \sum_{i,j} u_{ij} u_{ji} + \frac{1}{2}\kappa \left(\text{tr}(b_{ij})\right)^2 + \kappa_G \text{det}(b_{ij})\right]
$$

Growth can independently tune the metric tensor g_{ij} and the curvature tensor K_{ij} , which may not be compatible with any **surface shape that would produce zero energy cost!**

Zero energy shape exists only when preferred metric tensor g_{ij} **and** preferred curvature tensor K_{ij} satisfy Gauss-Codazzi-Mainardi relations!

Mechanics of growing sheets

One of the Gauss-Codazzi-Mainardi equations (Gauss's Theorema Egregium) relates the Gauss curvature to metric tensor

$$
\det(K_{ij}') = \mathcal{F}(g_{ij}')
$$

The equilibrium membrane shape $\vec{r}^{\,\prime}(x^1,x^2)$ **corresponds to the minimum of elastic energy:**

$$
U = \int \left(\sqrt{g} dx^1 dx^2\right) \left[\frac{1}{2}\lambda \left(\sum_i u_{ii}\right)^2 + \mu \sum_{i,j} u_{ij} u_{ji} + \frac{1}{2}\kappa \left(\text{tr}(b_{ij})\right)^2 + \kappa_G \text{det}(b_{ij})\right]
$$

scaling with membrane thickness d

 $\kappa, \kappa_G \sim E d^3$

 $\lambda, \mu \sim E d$

For very thin membranes the equilibrium shape matches the preferred metric tensor to avoid stretching, compressing and shearing. This also specifies the Gauss curvature!

$$
g'_{ij} = g_{ij}
$$

$$
\det(K'_{ij}) = \mathcal{F}(g_{ij})
$$

Wrinkled and straight blades in macroalgae

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Slow water flow environment (v~0.5 m/s)

faster than the midline

Fig. 4 Transverse growth strain rates (M W \mathbf{f} function of the distance from the origin (Fig. 1C) of each \mathbf{f} $\frac{1}{2}$ 13 **What is the effect of differential growth rate between the edge and the midline of the blade?**

Fast water flow environment (v~1.5 m/s)

edges of blades grow edges or blades grow at the **Example 19 Same speed as the midline faster than the midline edges of blades grow at the**

M. Koehl et al., <u>Integ. Comp.</u> Biol. **48**, 834 (2008) Day 0, for wide, ruffled blades on N. luetkeana growing at the Ω oron evident. In the rapid proximal regions of \mathcal{B} ruffled blades, the edges of the blade grew more hole marking a blade segment at the start of t \overline{D} iel 40, 904/0 at the slow-flow SC site (A), and for strap-like flat blades on

Differential growth produces internal stress point to light the specific distance from the specific specific to the specific specific specific specific spec and vertical neighbors. If the sheet remains flat, adjacent hor-

tical connecting springs more and more for longer and longer sheets. Something has to give the planet $\mathbf s$

faster growth of the **bottom edge in x direction**

hlata: If arquith in different h ples, but if you are the depth of the designation of the designation of the design and the designation of the d the cheet than the curveture the sheet, their the carvature turaan the tan and hattam of Note: If growth is different between the top and bottom of aneor K_{\pm} ie modified ae welll the sheet, then the curvature tensor $\,K_{ij}\,$ is modified as well!

Example

Assume that differential growth in x direction produces metric tensor of the form

◆

For thin membranes the metric tensor wants to be matched
$$
g'_{ij} = g_{ij}
$$

0*,* 1

 $\int f(y)$, 0

Gauss's Theorema Egregium provides Gauss curvature

$$
\det(K'_{ij}(y)) = \mathcal{F}(g_{ij}) = -\frac{1}{f} \frac{d^2 f(y)}{dy^2} = -\frac{1}{\lambda^2} \times \frac{ce^{(|y|-W)/\lambda}}{(1 + ce^{(|y|-W)/\lambda})} < 0
$$

For thin membranes faster growth on edges produces shapes that locally look like saddles!

 $g_{ij} =$

 $f(y)=1+ ce^{(|y|-W)/\lambda}$

Scaling analysis

membrane compression

H. Liang and L. Mahadevan, PNAS **106**, 22049 (2009) latory shapes of a long, growing ribbon as a function of the maximum edge **growth.** Liang and L. Manadevan, <u>PIVAS</u> **106**, 22049 (2009)

Shapes of flowers and leaves

Faster growth of the edge is consistent with observed saddles and edge wrinkles, which indeed correspond to the negative Gauss curvature!

saddles

wrinkled edges (+saddles)

Growth of a blooming lily

B **in lab blooming takes 4.5 days under constant fluorescent light (1 frame/min)**

H. Liang and L. Mahadevan, **PNAS 108**, 5516 (2011) further quantify the role of the middle opening, we can also the middle of the mi

How flowers open in the morning and close in the evening?

https://vimeo.com/98276732

How flowers open in the morning and close in the evening?

morning evening

When temperature increases in the morning, flowers regulate their growth pattern to grow more new cells on the inside of flower leaves. This results in curling of leaves and opening of flowers.

When temperature drops in the evening, flowers regulate their growth pattern to grow more new cells on the outside of flower leaves. This results in straightening of leaves and closing of flowers.